

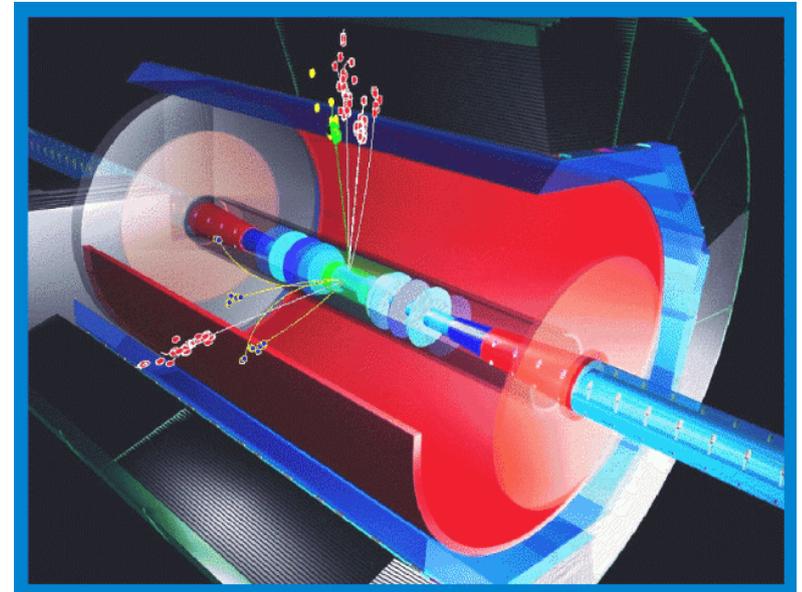
Simulation and Reconstruction Software for the ILC

Frank Gaede
DESY

FNAL ILC Computing Seminar
September 25, 2006

Outline

- Introduction to ILC
- Overview international software for the ILC
- LDC Software Tools
 - **LCIO** – data model & persistency
 - **Mokka** – geant4 full simulation
 - **Marlin** – C++ framework
 - **MarlinReco** – reconstruction toolkit
 - **LCCD** - conditions data toolkit
 - **GEAR** – geometry description
- Interoperability
- Summary/Outlook



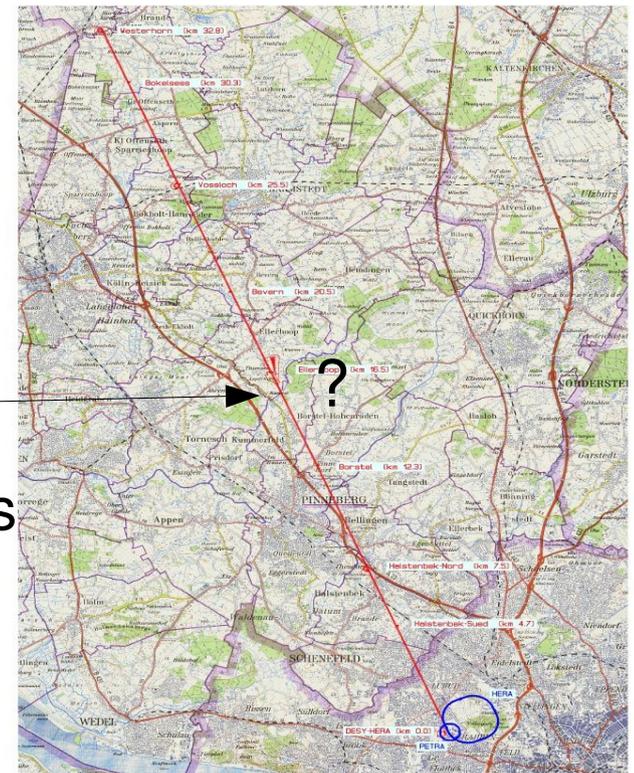
ILC Overview I

- future linear collider (e⁺/e⁻) project
 - >30km length
 - 1stage
 - energy 200→500 GeV, scannable
 - 500 fb⁻¹ in first 4 years
 - 2nd stage
 - energy upgrade to ~1TeV
 - ~1000 fb⁻¹ in 3-4 years
- options
 - gama/gamma, gamma/e⁻, e⁻/e⁻, Giga-Z
 - 2 IRs for 2 experiments ?



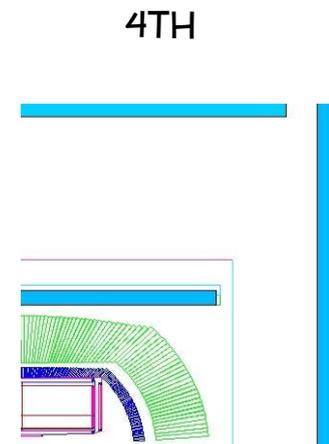
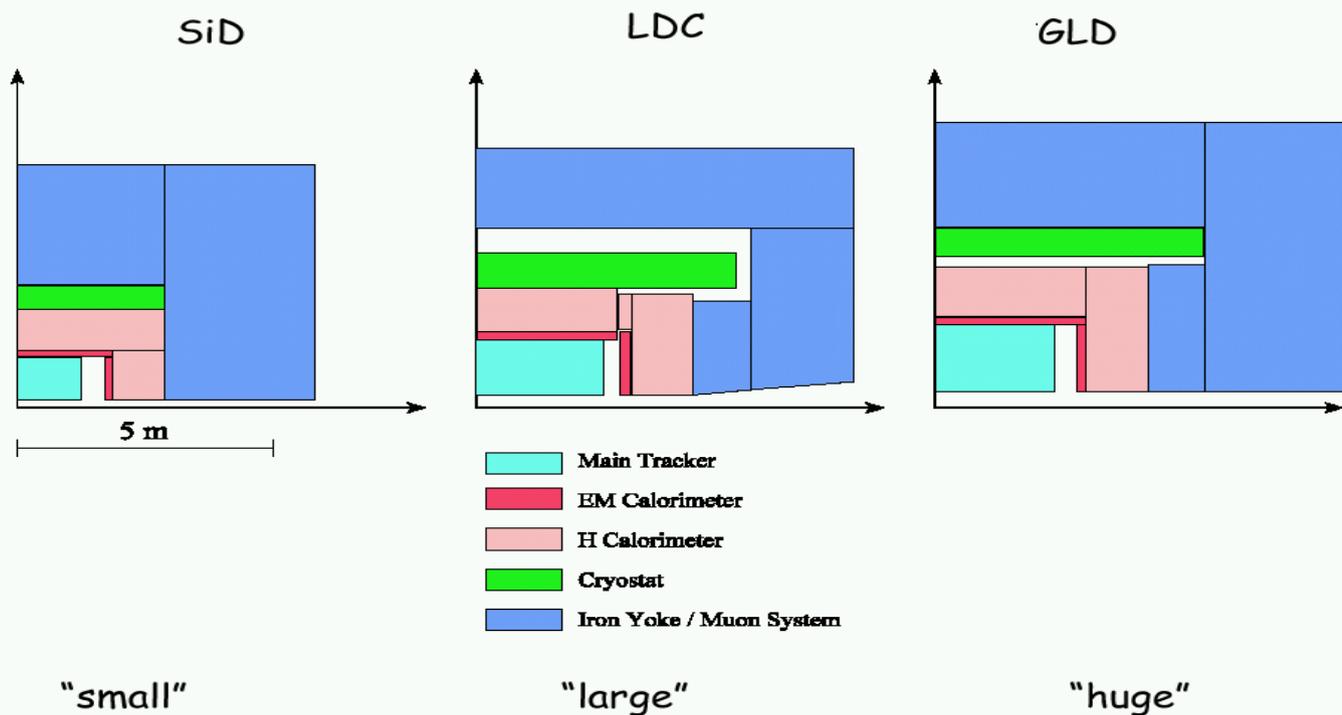
ILC Overview II

- originally three regional projects (~1991(!?)-2004)
 - America: NLC Asia: JLC Europe: Tesla
- now: **International Linear Collider - ILC**
- ITRP technology decision (Aug 2004):
 - “We recommend that LC be based on **super-conducting RF** technology.”
- rough timeline (planned):
 - (2005) Accelerator CDR
 - (2007) Accelerator TDR – Detector CDRs from concept study (next slide)
 - (2008/09?) LC site selection
 - (2009/10?) Global lab selects experiments
 - (?) Start construction
 - (??) Data



ILC Detector Concept Studies

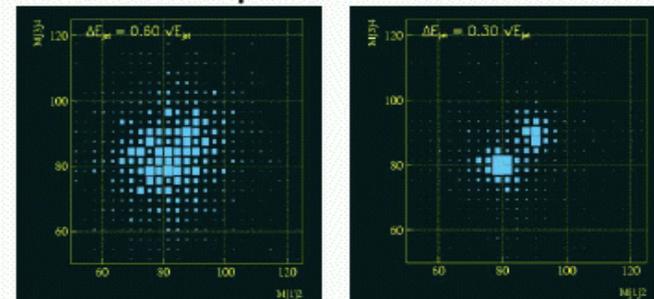
- **WWS** (WorldWide Study on Physics and Detector for Future Linear Colliders) :
 - coordinate studies on four **interregional detector concepts**, and work toward detector TDRs (2007/2008):
 - currently ongoing: work on DODs



Reconstruction @ the ILC

- general ILC detector features:
 - precision tracking
 - precision vertexing
 - high granularity in calorimeters
 - (Ecal ~1cm, Hcal ~1-5cm)
- important: **very high jet-mass resolution** ~30%/sqrt(E/GeV)

WW-ZZ separation



Particle Flow

- reconstruct all single particles
- use tracker for charged particles
- use Ecal for photons
- use Hcal for neutral hadrons

why develop reconstruction sw now ?

- reconstruction algorithms (pflow) are part of the overall detector performance
- need full reconstruction to optimize detector concepts

dominant contribution (E<50 GeV):

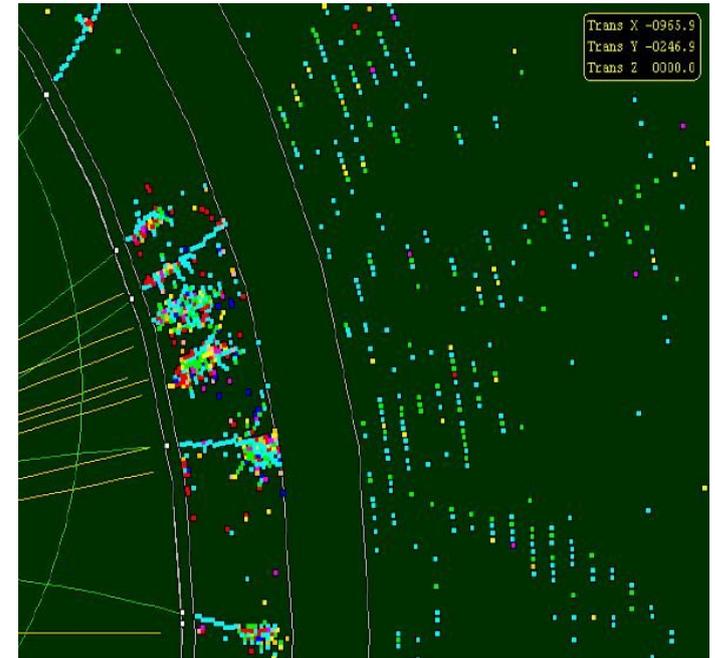
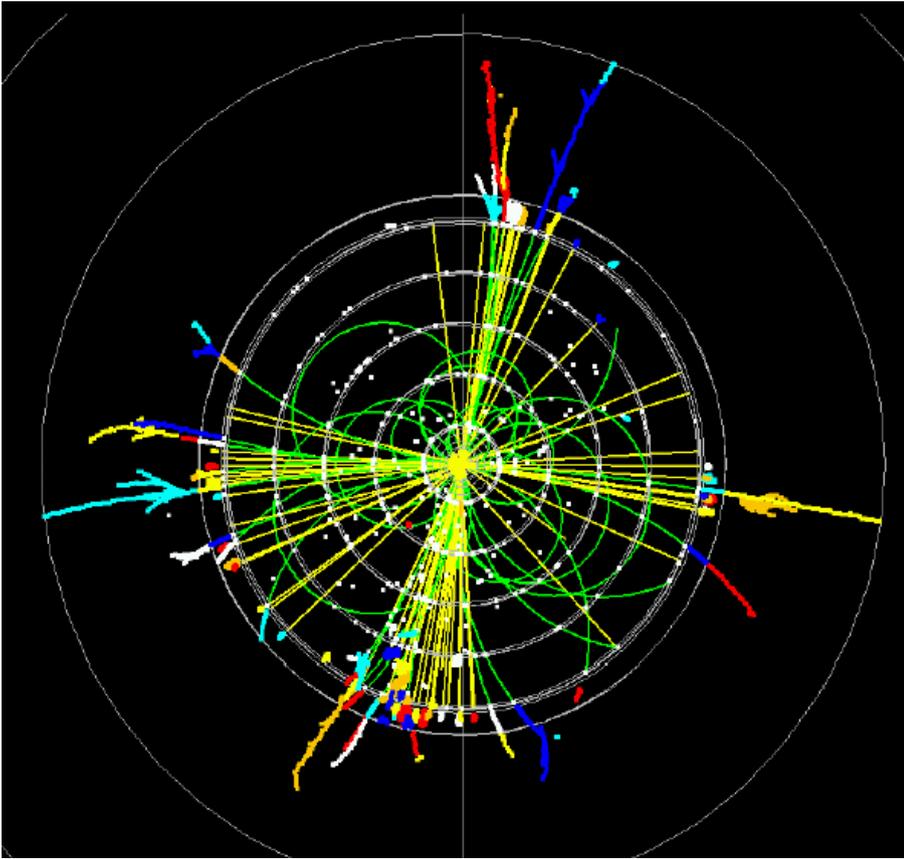
- Hcal resolution
- confusion term

$$\sigma_{E_{jet}}^2 = \epsilon_{trk}^2 \sum_i E_{trk,i}^4 + \epsilon_{ECal}^2 E_{ECal} + \epsilon_{HCal}^2 E_{HCal} + \sigma_{confusion}^2$$

$$\epsilon_{trk} = \delta(1/p) \approx 5 \cdot 10^{-5}, \quad \epsilon_{ECal} = \frac{\delta E}{\sqrt{E}} \approx 0.1, \quad \epsilon_{HCal} \approx 0.5$$

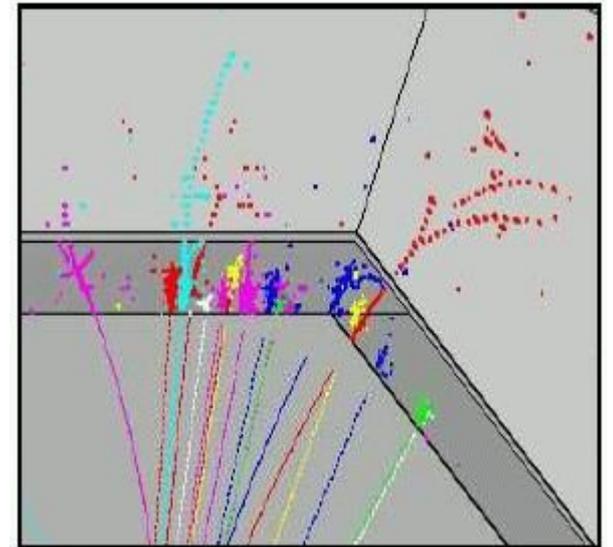
Imaging calorimeter & ParticleFlow

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Need software tools to improve clustering & pflow:

- detailed hadronic shower simulation (**Geant4**)
- framework for developing and comparing pflow algorithms



Note: precision tracking and vertexing also very challenging and important !

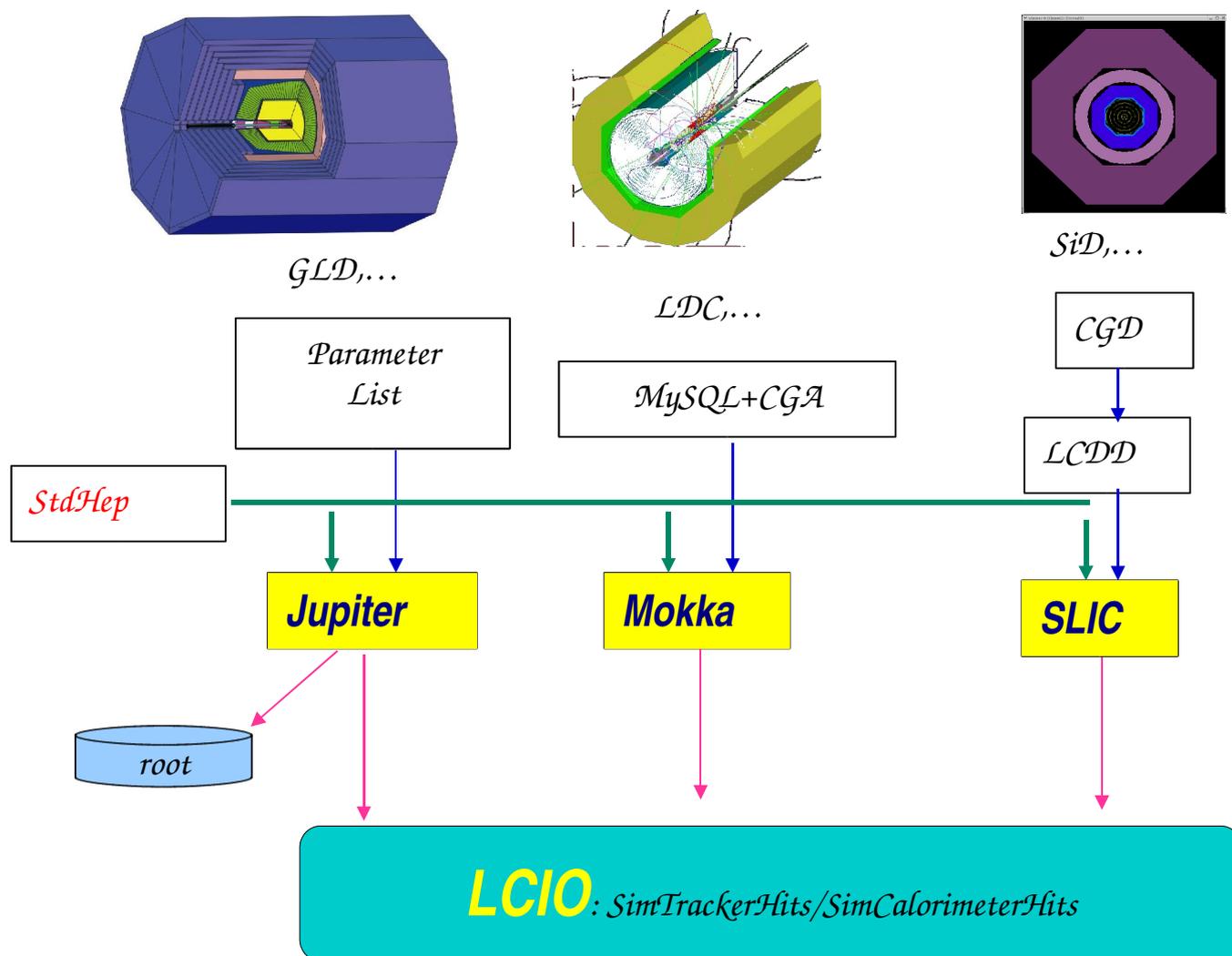
ILC software packages

	Description	Detector	Language	IO-Format	Region
Simdet	fast Monte Carlo	TeslaTDR	Fortran	StdHep/LCIO	EU
SGV	fast Monte Carlo	simple Geometry, flexible	Fortran	None (LCIO)	EU
Lelaps	fast Monte Carlo	SiD, flexible	C++	SIO, LCIO	US
Mokka	full simulation – Geant4	TeslaTDR, LDC, flexible	C++	ASCI, LCIO	EU
SLIC	full simulation – Geant4	SiD, flexible	C++	LCIO	US
Jupiter	full simulation – Geant4	JLD (GDL)	C++	Root (LCIO)	AS
Marlin	reconstruction and analysis application framework	Flexible	C++	LCIO	EU
org.lcsim	reconstruction framework (under development)	SiD (flexible)	Java	LCIO	US
Jupiter-Satelite	reconstruction and analysis	JLD (GDL)	C++	Root	AS
LCCD	Conditions Data Toolkit	All	C++	MySQL, LCIO	EU
LCDD	Geometry description	SiD (flexible)	Java/C++	XM/GDML	US
GEAR	Geometry description	Flexible	C++ (Java?)	XML	EU
LCIO	Persistency and datamodel	All	Java, C++, Fortran	-	AS,EU,US
JAS3/WIRED	Analysis Tool / Event Display	All	Java	xml,stdhep, hepdep,LCIO,	US,EU

not included: proposed ILCroot/Aliroot

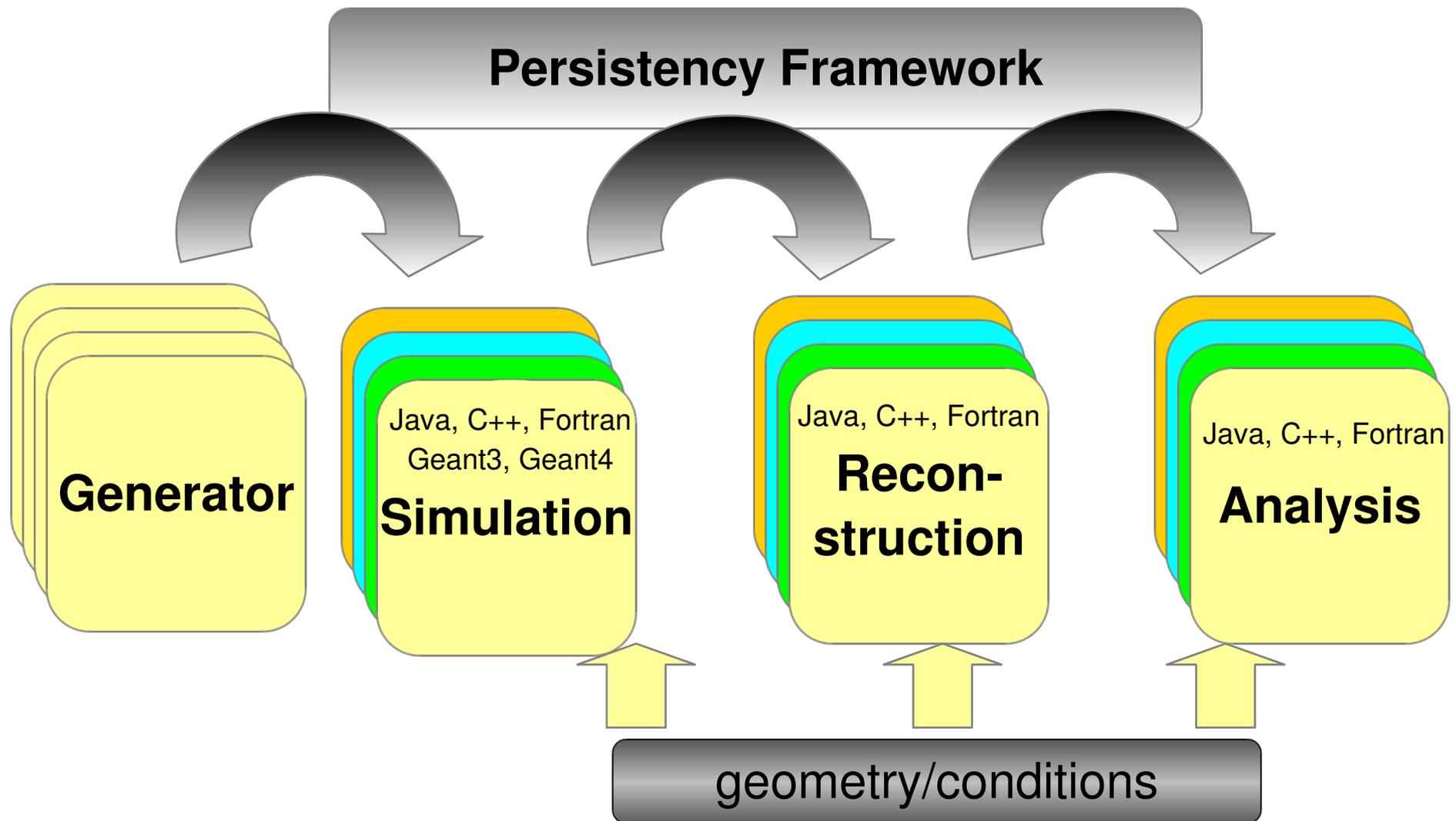
ILC Simulation Frameworks (Geant4)

- *Geant4, StdHep and LCIO are common feature*
- *Each trying to be generic with different approach
different ways to define geometries*

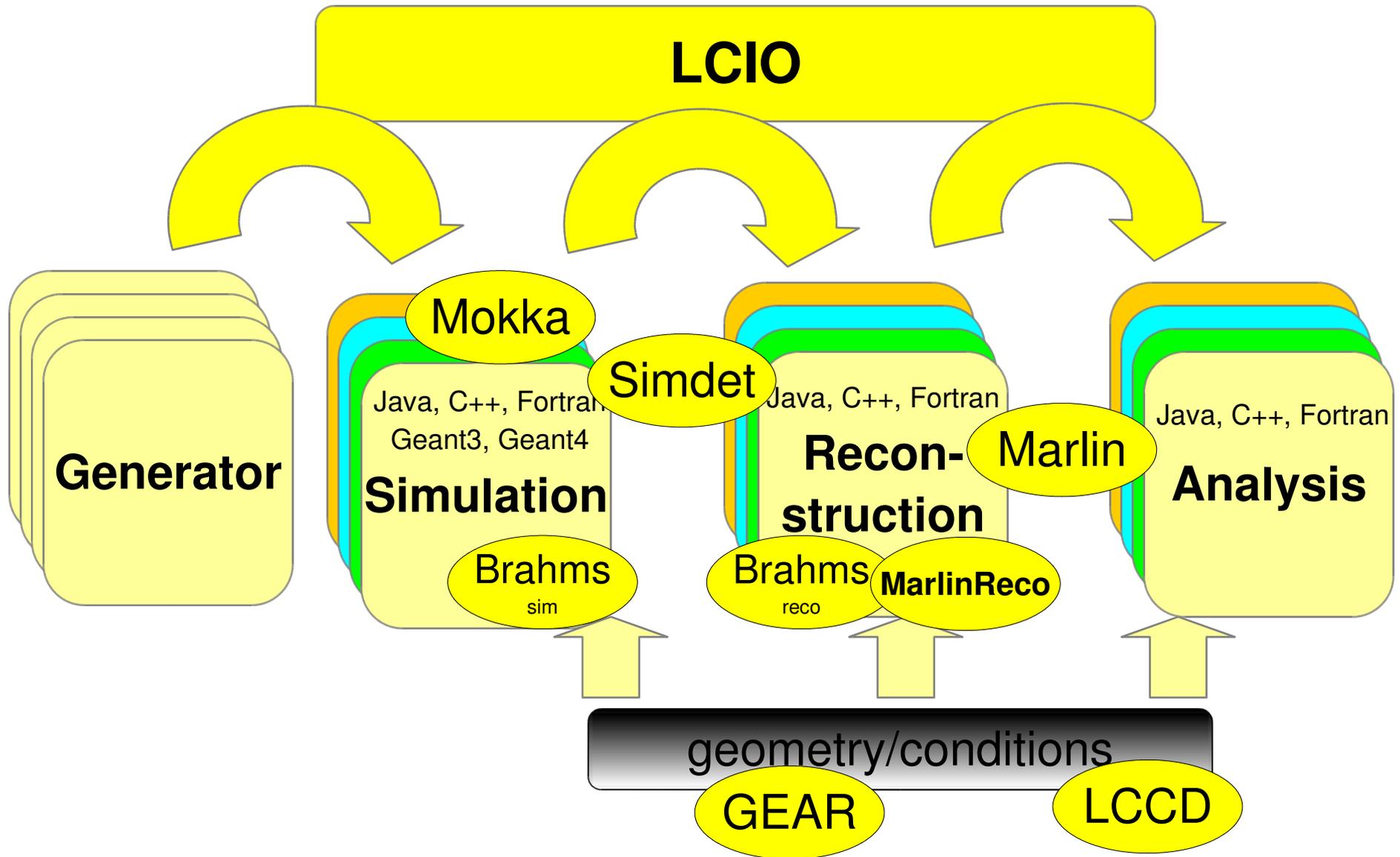


(A.Miyamoto)

ILC software chain



ILC software tools used for LDC



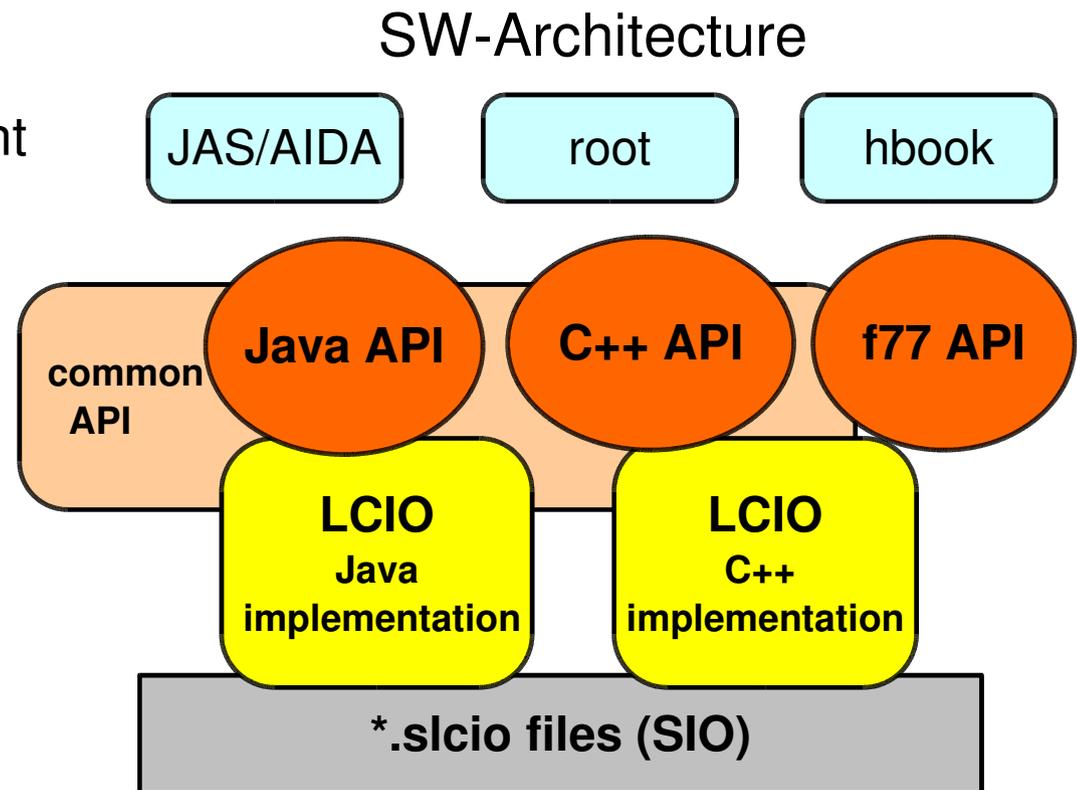
LCIO overview

- DESY and SLAC joined project:
 - provide common basis for ILC software
- Features:
 - Java, C++ and f77 (!) API
 - extensible data model for current and future simulation and testbeam studies
 - user code separated from concrete data format
 - no dependency on other frameworks

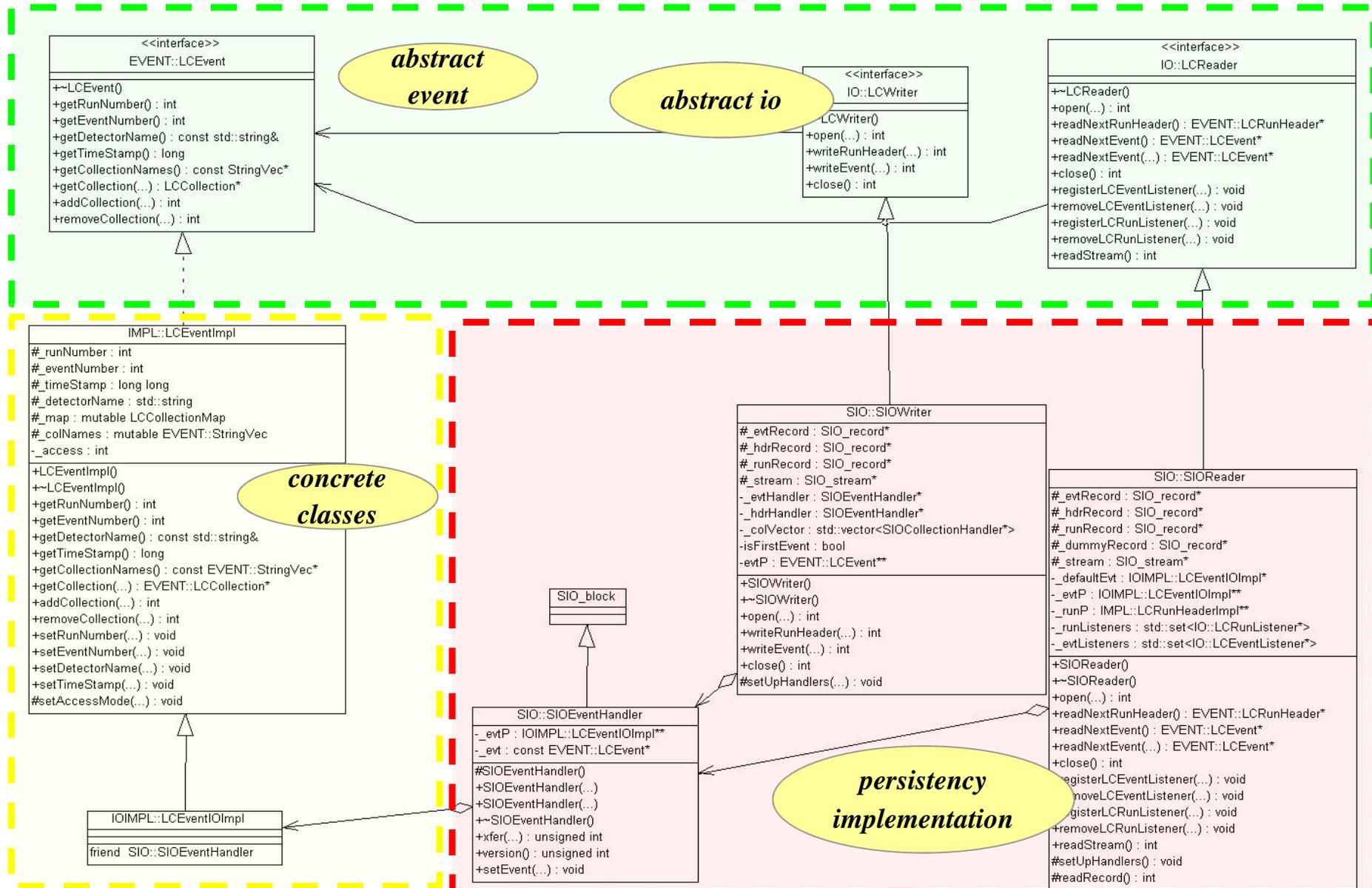
simple & lightweight

current release: **v01-07**

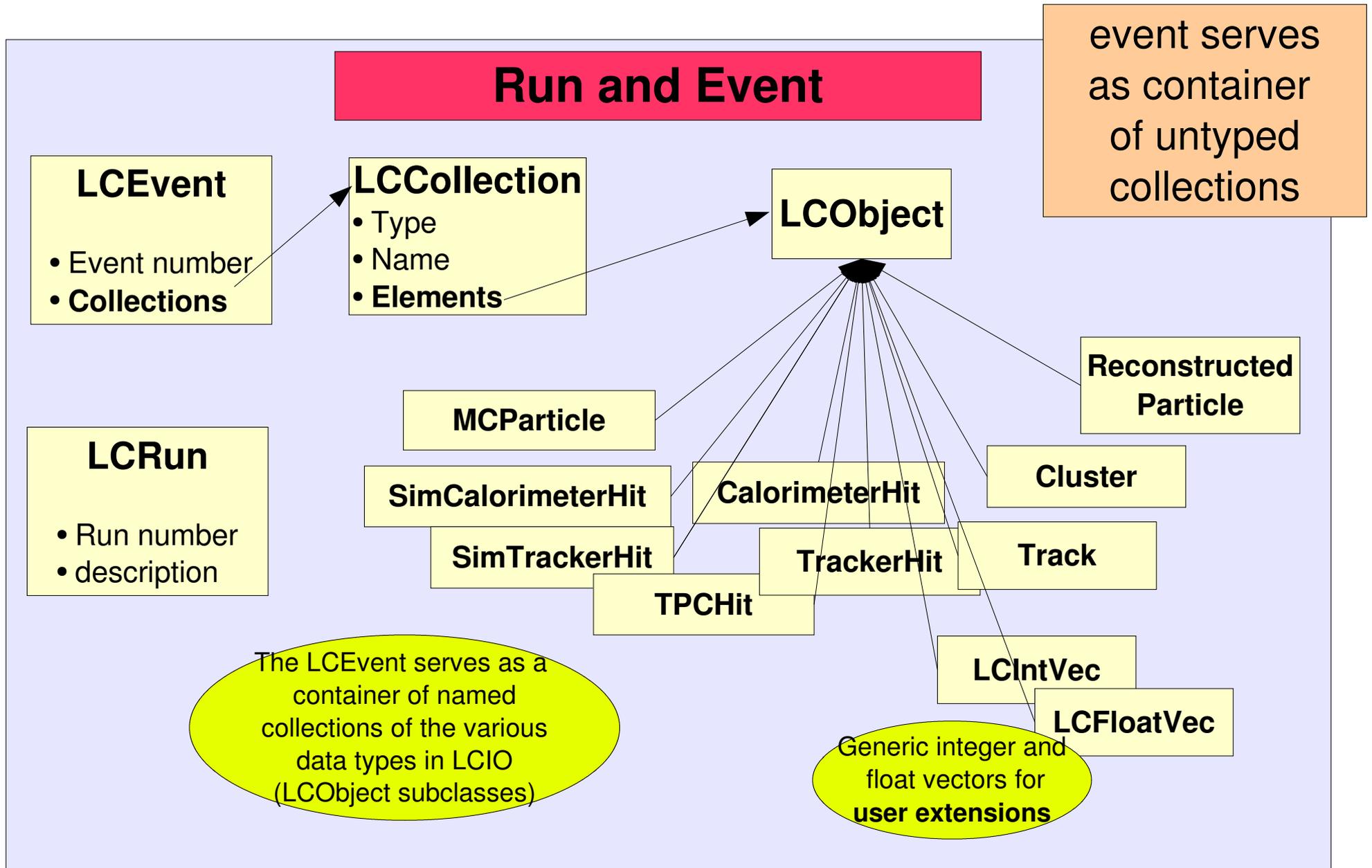
now de facto standard
persistency & datamodel
for ILC software



LCIO class design

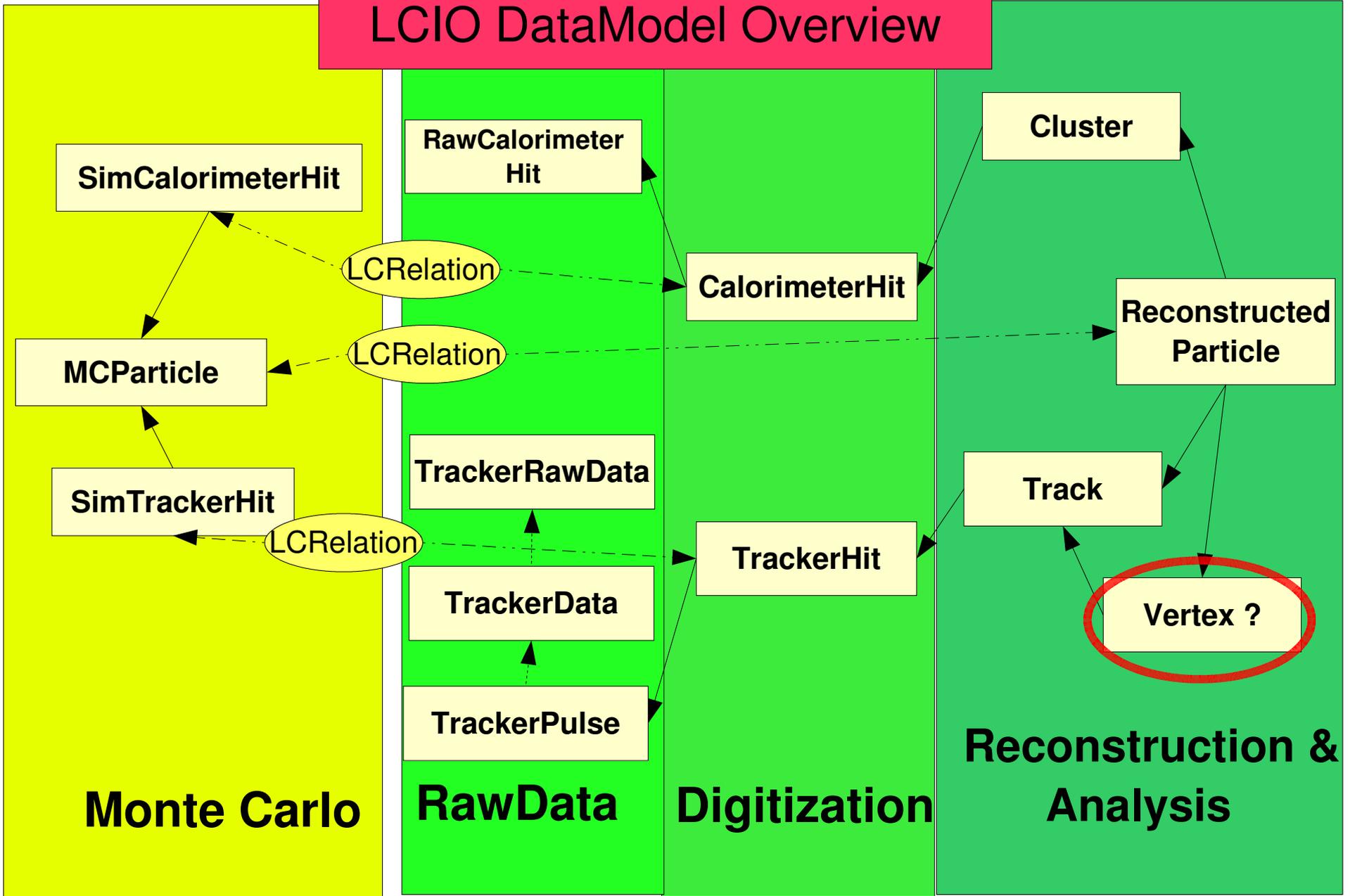


LCIO Event Data Model I



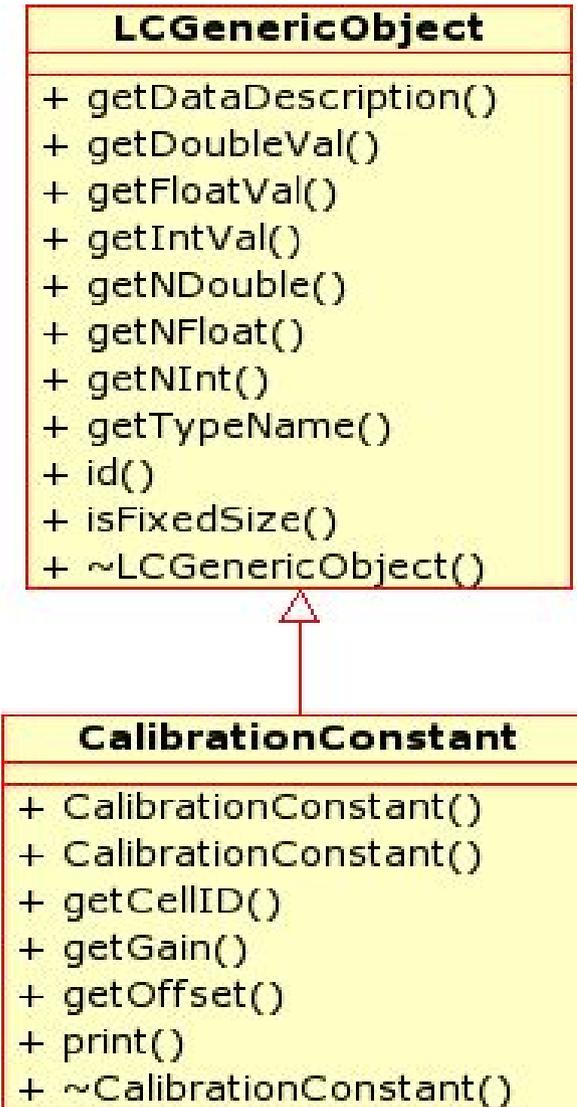
LCIO Event Data Model II

LCIO DataModel Overview



LCIO – Generic User Information

- LCIO data model defines the object needed for ILC simulation studies, but
 - users want additional information in files for specific studies
 - can't create new classes within LCIO for all requests and purposes
 - need generic user class:
LCGenericObject
 - almost arbitrary data objects
 - typically access provided through user subclass - but not needed:
 - has description string for reading the data without need to have access to data dictionary (library)

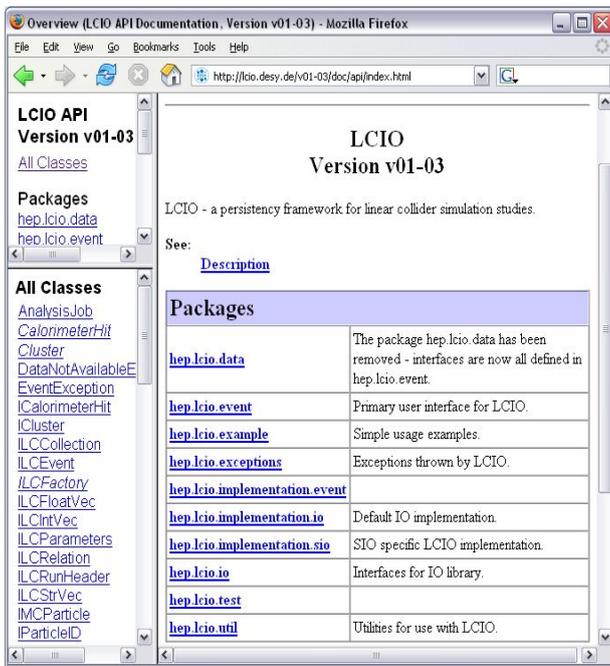


LCIO Event Data Model III

- the LCIO event data model is fairly complete and flexible
- however it is adapted and extended as needed by the community
 - maintaining downward compatibility
 - with international discussion and agreement
- example: introduction of a new **Vertex** class in LCIO
 - originally proposed by LCFI group
 - see discussion @ <http://forum.linearcollider.org/>
 - new raw data classes for prototypes

LCIO Online documentation

Frank Gaede, FNAL ILC Computing Seminar, September 25, 2006



Overview (LCIO API Documentation, Version v01-03) - Mozilla Firefox
http://lco.desy.de/v01-03/doc/api/index.html

LCIO API Version v01-03
All Classes

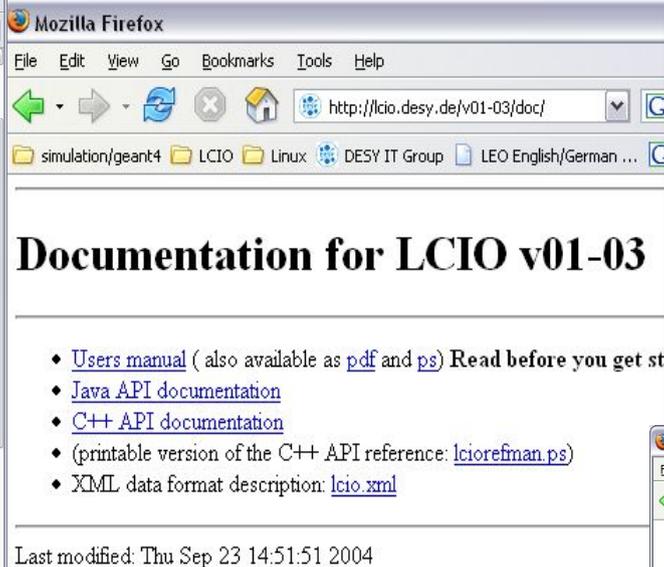
Packages
hep.lcio.data
hep.lcio.event

All Classes
AnalysisJob
CalorimeterHit
Cluster
DataNotAvailableE
EventException
ICalorimeterHit
ICluster
ILCCollection
ILCEvent
ILCFactory
ILCFloatVec
ILCIntVec
ILCParameters
ILCRelation
ILCRunHeader
ILCStrVec
IMCParticle
IParticleID

LCIO - a persistency framework for linear collider simulation studies.

See:
Description

Package	Description
hep.lcio.data	The package hep.lcio.data has been removed - interfaces are now all defined in hep.lcio.event.
hep.lcio.event	Primary user interface for LCIO.
hep.lcio.example	Simple usage examples.
hep.lcio.exceptions	Exceptions thrown by LCIO.
hep.lcio.implementation.event	
hep.lcio.implementation.io	Default IO implementation.
hep.lcio.implementation.sio	SIO specific LCIO implementation.
hep.lcio.io	Interfaces for IO library.
hep.lcio.test	
hep.lcio.util	Utilities for use with LCIO.



Mozilla Firefox
http://lco.desy.de/v01-03/doc/

Documentation for LCIO v01-03

- [Users manual](#) (also available as [pdf](#) and [ps](#)) Read before you get st
- [Java API documentation](#)
- [C++ API documentation](#)
- (printable version of the C++ API reference: [lciorefman.ps](#))
- XML data format description: [lcio.xml](#)

Last modified: Thu Sep 23 14:51:51 2004



LCIO - Users manual v01-03 - Mozilla Firefox
http://lco.desy.de/v01-03/doc/manual_html/manual.html

Building the library

A few variables have to be set depending on your development environment, e.g.

- **Linux (and bash):**

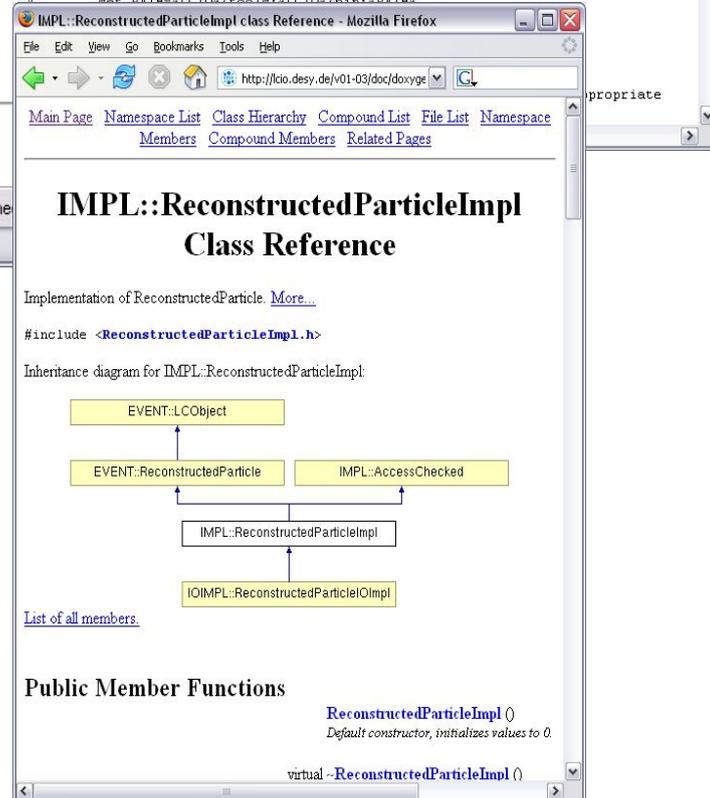
```
export LCIO=/lcio/v01-03          <-- modify as appropriate
export PATH=$LCIO/tools:$PATH

export JDK_HOME=/usr/lib/j2sdk   <-- modify as appropriate
```

- **Windows/Cygwin - DOS shell:**

```
set PATH=c:/cygwin/bin;%PATH%   <-- modify as appropriate

set LCIO=c:/lcio/develop/v01-03 <-- modify as appropriate
set JDK_HOME=c:/j2sdk1.4.1_01  <-- modify as appropriate
```



IMPL::ReconstructedParticleImpl class Reference - Mozilla Firefox
http://lco.desy.de/v01-03/doc/doxyge

IMPL::ReconstructedParticleImpl Class Reference

Implementation of ReconstructedParticle. [More...](#)

```
#include <ReconstructedParticleImpl.h>
```

Inheritance diagram for IMPL::ReconstructedParticleImpl:

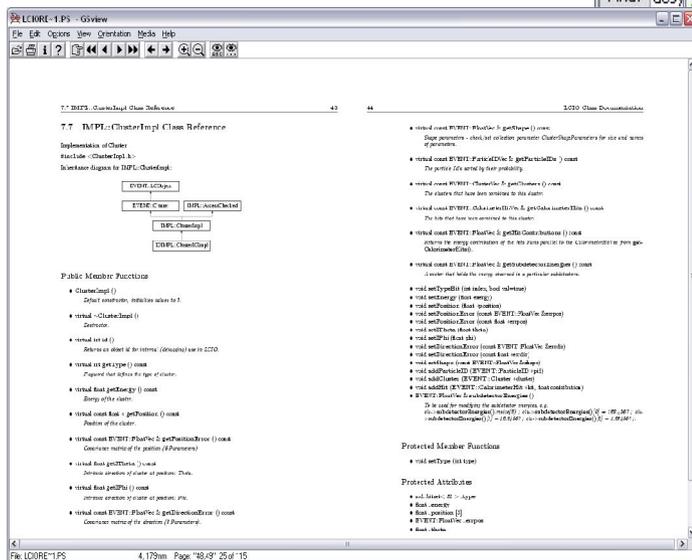
```
graph TD
    EVENT_LCObject[EVENT::LCObject] --> EVENT_ReconstructedParticle[EVENT::ReconstructedParticle]
    EVENT_ReconstructedParticle --> IMPL_AccessChecked[IMPL::AccessChecked]
    IMPL_AccessChecked --> IMPL_ReconstructedParticleImpl[IMPL::ReconstructedParticleImpl]
    IMPL_ReconstructedParticleImpl --> IOIMPL_ReconstructedParticleIOImpl[IOIMPL::ReconstructedParticleIOImpl]
```

[List of all members.](#)

Public Member Functions

```
ReconstructedParticleImpl()
    Default constructor, initializes values to 0.

virtual ~ReconstructedParticleImpl()
```



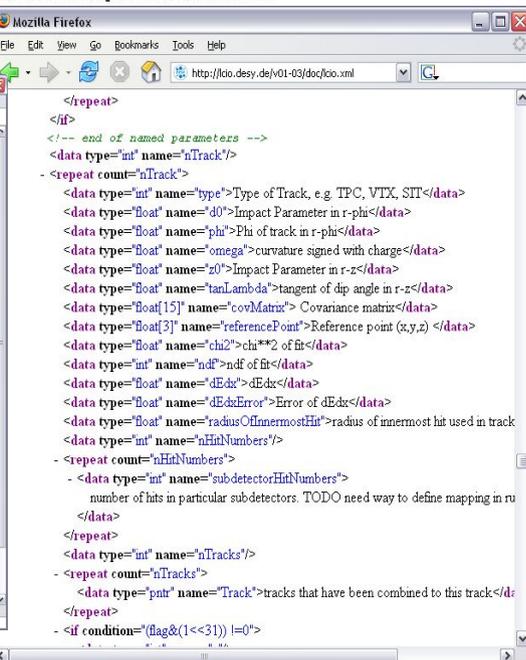
LORE-1PS Overview

7.7 IMPL::ClusterImpl Class Reference

Implementation of Cluster

Public Member Functions

- ClusterImpl()
- ClusterImpl(const ClusterImpl &)
- ~ClusterImpl()
- virtual void setType() const
- virtual void setEnergy() const
- virtual void setPhi() const
- virtual void setTheta() const
- virtual void setRho() const
- virtual void setZ() const
- virtual void setPhi2() const
- virtual void setTheta2() const
- virtual void setRho2() const
- virtual void setZ2() const
- virtual void setPhi3() const
- virtual void setTheta3() const
- virtual void setRho3() const
- virtual void setZ3() const



Mozilla Firefox
http://lco.desy.de/v01-03/doc/lco.xml

```
<!-- end of named parameters -->
<data type="int" name="nTrack"/>
<repeat count="nTrack">
  <data type="int" name="type">Type of Track, e.g. TPC, VTX, SIT</data>
  <data type="float" name="d0">Impact Parameter in r-phi</data>
  <data type="float" name="phi">Phi of track in r-phi</data>
  <data type="float" name="omega">curvature signed with charge</data>
  <data type="float" name="z0">Impact Parameter in r-z</data>
  <data type="float" name="tanLambd">tangent of dip angle in r-z</data>
  <data type="float[15]" name="covMatrix"> Covariance matrix</data>
  <data type="float[3]" name="referencePoint">Reference point (x,y,z) </data>
  <data type="float" name="chi2">chi**2 of fit</data>
  <data type="int" name="ndf">ndf of fit</data>
  <data type="float" name="dEdx">dEdx</data>
  <data type="float" name="dEdxError">Error of dEdx</data>
  <data type="float" name="radiusOfInnermostHit">radius of innermost hit used in track</data>
  <data type="int" name="nHitNumbers">
    <repeat count="nHitNumbers">
      <data type="int" name="subdetectorHitNumbers">
        number of hits in particular sub-detectors. TODO need way to define mapping in ru
      </data>
    </repeat>
  </data>
  <repeat count="nTracks">
    <data type="int" name="nTracks">
      <repeat count="nTracks">
        <data type="int" name="Track">tracks that have been combined to this track</data>
      </repeat>
    </data>
  </repeat>
  <!-- if condition="(flag&(1<<31))!=0" -->
```

Simulation tools: Simdet, Brahms

• **SIMDET**

writes LCIO

- parameterized fast Monte Carlo (f77)
- tracks + cov. matrix and clusters
- hard coded geometry: TESLA TDR Detector

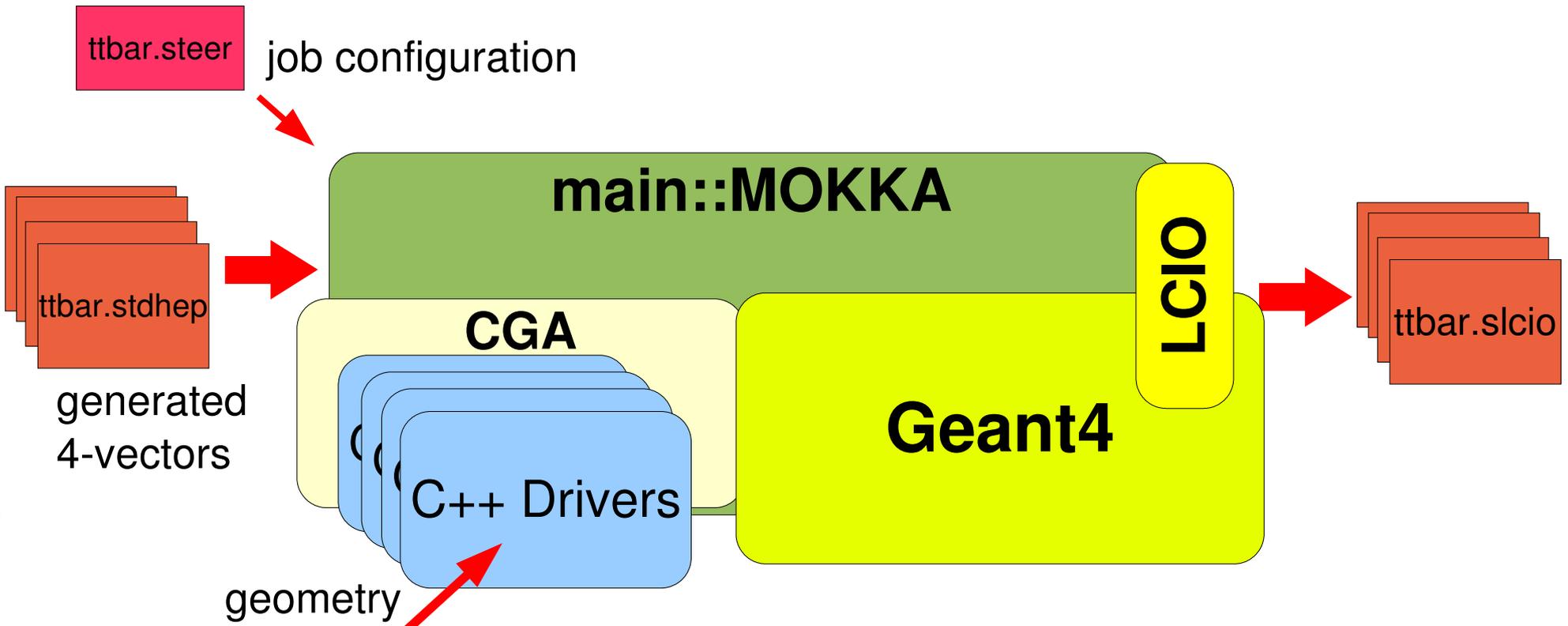
• **Brahms**

reads + writes LCIO

- geant3 full simulation (f77)
- hard coded geometry: TESLA TDR Detector
- full standalone reconstruction part (pflow)
 - tracking based on LEP reconstruction code

for download (cvs web interface)
and more information:
http://www-zeuthen.desy.de/linear_collider

Mokka overview



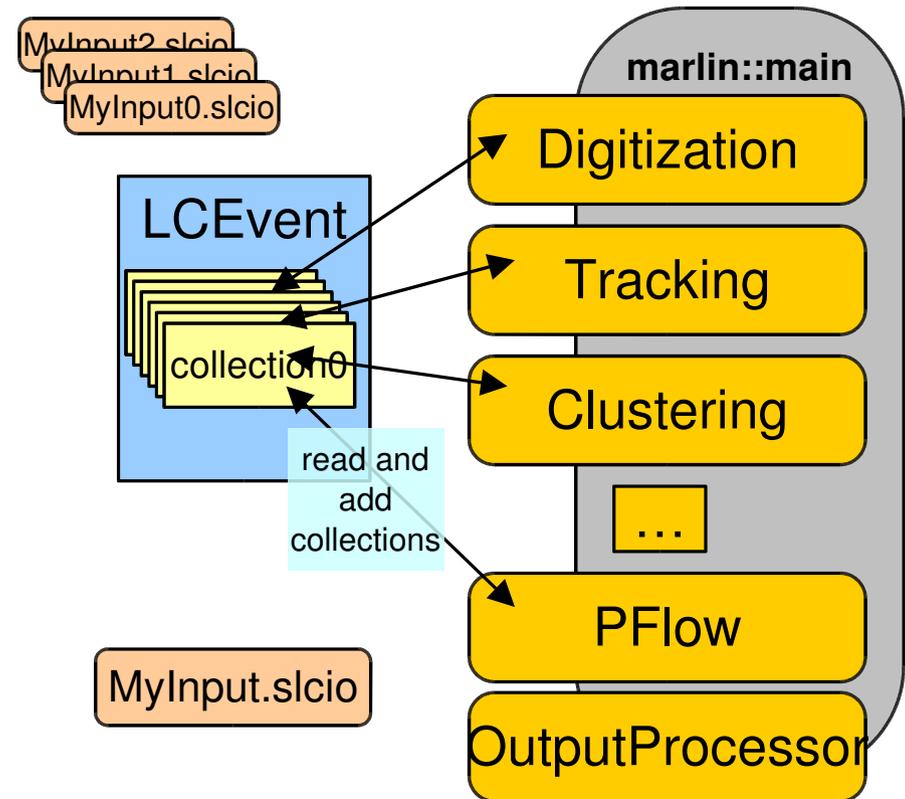
MySQL

- developed at LLR (ecole polytechnique)
- writes LCIO
- uses MySQL DB + geometry drivers
- flexible geometry setup on subdetector basis:
 - Tesla TDR / LDC
 - SiD
 - Calice testbeam prototypes
- [used in European/ LDC study](#)

Marlin

Modular **A**nalysis & **R**econstruction for the **L I N**ear Collider

- modular C++ **application framework** for the analysis and reconstruction of LCIO data
- uses **LCIO** as transient data model
- software modules called Processors
- provides main program !
- provides simple user steering:
 - program flow (active processors)
 - user defined variables
 - per processor and global
 - input/output files
 - **Plug&Play** of processors



Marlin Processor

- provides main **user callbacks**
- has **own set of input parameters**
 - int, float, string (single and arrays)
 - parameter description
- naturally modularizes the application
- **order of processors is defined via steering file:**
 - easy to exchange one or several modules w/o recompiling
 - can run the same processor with different parameter set in one job
- **processor task can be as simple as creating one histogram or as complex as track finding and fitting in the central tracker**

```
marlin::Processor
init()
processRunHeader(LCRunHeader* run)
processEvent( LCEvent* evt)
check( LCEvent* evt)
end()
```

```
UserProcessor
processEvent( LCEvent* evt){
    // your code goes here...
}
```



Marlin core features

- fully configurable through steering files:
 - program flow
 - input parameters (processor based and global)
- self-documenting:
 - `./bin/Marlin -x`
prints example steering file with
all available processors with their parameters and example/default values
- AIDA interface for histogramming
 - easy creation of histograms through abstract interface
 - AIDAJNI/JAIDA, RAIDA (root based), ...
- configurable output
 - drop collections by name/type
- simple examples
 - user processor template, GNUmakefile,...
- easily extensible
 - makefiles 'automatically' include user packages with processors

Marlin – XML steering files

```
- <marlin>
- <execute>
  <processor name="MyAIDAProcessor"/>
  <processor name="MyEventSelection"/>
  - <if condition="MyEventSelection">
    <group name="Tracking"/>
    <processor name="MyClustering"/>
    <processor name="MyPFlow"/>
    <processor name="MyLCIOOutputProcessor"/>
  </if>
</execute>
- <global>
  <parameter name="LCIOInputFiles"> simjob.slcio </parameter>
  <parameter name="MaxRecordNumber" value="5001"/>
  <parameter name="SupressCheck" value="false"/>
</global>
- <processor name="MyLCIOOutputProcessor" type="LCIOOutputProcessor">
  <parameter name="LCIOOutputFile" type="string">outputfile.slcio </parameter>
  <parameter name="LCIOWriteMode" type="string">WRITE_NEW</parameter>
</processor>
- <group name="Tracking">
  <parameter name="NTPCLayers" value="200"/>
  <processor name="MyTrackfinder" type="Trackfinder"/>
  - <processor name="MyTrackfitter" type="Trackfitter">
    <parameter name="Algorithm" value="DAF"/>
  </processor>
</group>
<!-- ... -->
</marlin>
```

- Program flow defined in <execute>...</execute> section
- logical conditions from parameters evaluated at runtime

- global Parameters defined in <global/> section

- local Parameters defined in mandatory <parameter/> section

- Processors can be enclosed by <group/> tag
- Parameters in <group/> joined by all processors

a Marlin application is fully configured through the steering files
(no user main program) !!

Marlin Status and Plans

- current version: v00-09-05:
- some new features:
 - made compatible with CLHEP 2.x
 - made compatible with RAIDA
 - split outputfiles wrt. size: ttbar_000.slcio, ttbar_001.slcio,...
 - bug fixes
- plans:
 - improve dealing with and creation of steering files
 - show parameters in order specified
 - provide minimal steering files
 - provide help for one single processor
 - user suggestions/ needs ?

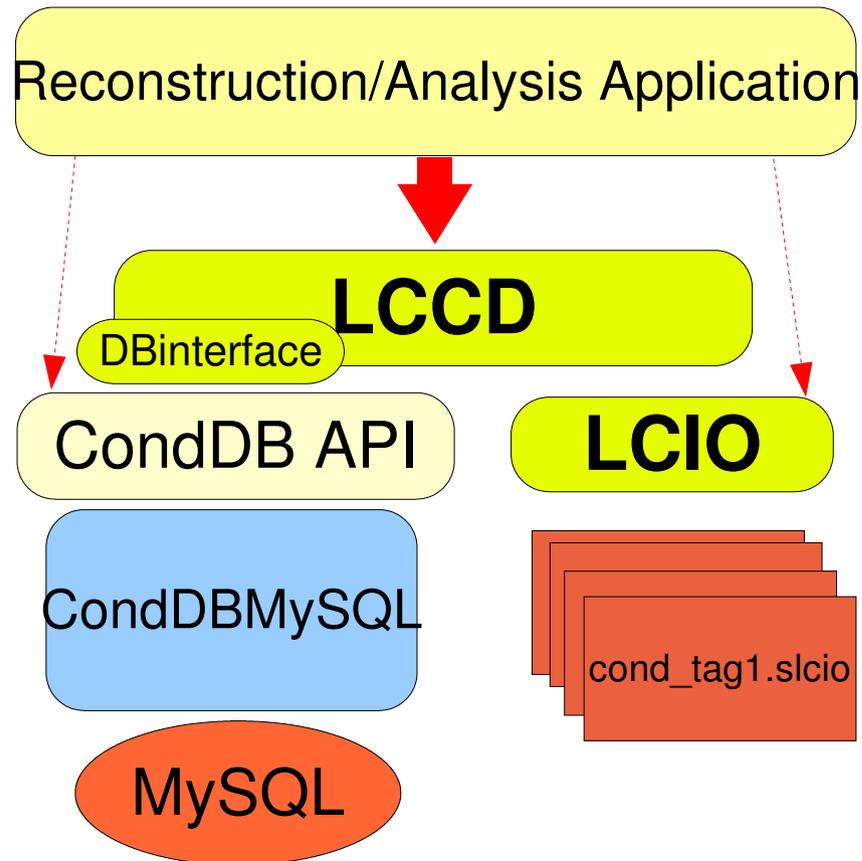
Marlin for reconstruction

- Marlin is a generic framework for processing of ILC data (LCIO)
 - simple and lightweight, depends on LCIO only
- some ingredients for typical reconstruction are missing:
 - description of detector geometry
 - conditions data (testbeam)
 - utility software, math libraries, ...
- optionally Marlin supports additional tools:
 - **GEAR** – geometry description
 - **LCCD** – conditions data
 - MarlinUtil – utility library

LCCD

Linear **C**ollider **C**onditions **D**ata Toolkit

- Reading conditions data
 - from conditions database
 - from simple LCIO file
 - from LCIO data stream
 - from dedicated LCIO-DB file
- Writing conditions data
 - tag conditions data
- Browse the conditions database
 - through creation of LCIO files
 - vertically (all versions for timestamp)
 - horizontally (all versions for tag)



LCCD is used by Calice for the conditions data of the ongoing testbeam studies

Gear

GEometry API for RReconstruction

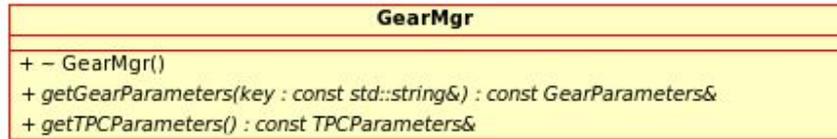
```
- <gear>
- <!--
  Example XML file for GEAR describing the LDC detector
-->
- <detectors>
- <detector id="0" name="TPCTest" geartype="TPCParameters" type="TPCParameters">
  <maxDriftLength value="2500."/>
  <driftVelocity value=""/>
  <readoutFrequency value="10"/>
  <PadRowLayout2D type="FixedPadSizeDiskLayout" rMin="386.0"
  maxRow="200" padGap="0.0"/>
  <parameter name="tpcRPhiResMax" type="double"> 0.16 </parameter>
  <parameter name="tpcZRes" type="double"> 1.0 </parameter>
  <parameter name="tpcPixRP" type="double"> 1.0 </parameter>
  <parameter name="tpcPixZ" type="double"> 1.4 </parameter>
  <parameter name="tpcIonPotential" type="double"> 0.00000003
</detector>
- <detector name="EcalBarrel" geartype="CalorimeterParameters">
  <layout type="Barrel" symmetry="8" phi0="0.0"/>
  <dimensions inner_r="1698.85" outer_z="2750.0"/>
  <layer repeat="30" thickness="3.9" absorberThickness="2.5"/>
  <layer repeat="10" thickness="6.7" absorberThickness="5.3"/>
</detector>
- <detector name="EcalEndcap" geartype="CalorimeterParameters">
  <layout type="Endcap" symmetry="2" phi0="0.0"/>
  <dimensions inner_r="320.0" outer_r="1882.85" inner_z="2820.0"/>
  <layer repeat="30" thickness="3.9" absorberThickness="2.5"/>
  <layer repeat="10" thickness="6.7" absorberThickness="5.3"/>
</detector>
</detectors>
</gear>
```

compatible with US – compact format

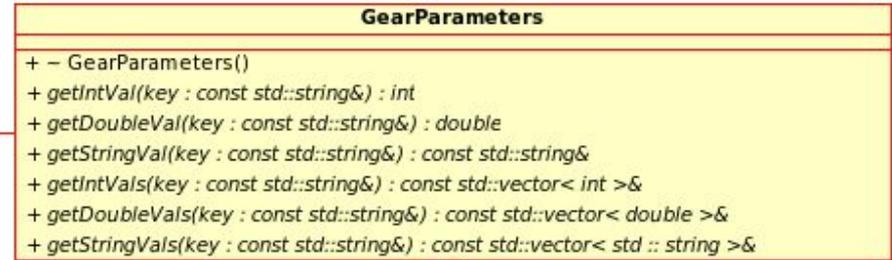
- well defined geometry definition for reconstruction that
 - is flexible w.r.t different detector concepts
 - has high level information needed for reconstruction
 - provides access to material properties - planned
- abstract interface (a la LCIO)
- concrete implementation based on XML files
- and Mokka-CGA

GEAR example:TPC description

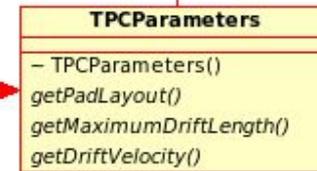
holds all subdetector classes



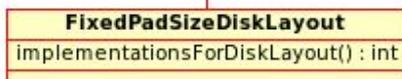
named parameters for additional attributes



can be also used for FTD, CaloEndcap,...



TPC specific parameters



implementation for disk with pad rings

GEAR – material properties

GearDistanceProperties

```
– GearDistanceProperties()
getMaterialNames(p0 : const Point3D&, p1 : const Point3D&) : const std::vector< std :: string >&
getMaterialThicknesses(p0 : const Point3D&, p1 : const Point3D&) : const std::vector< double >&
getNRadlen(p0 : const Point3D&, p1 : const Point3D&) : double
getNIntlen(p0 : const Point3D&, p1 : const Point3D&) : double
getBdL(pos : const Point3D&) : double
getEdL(pos : const Point3D&) : double
```

- proposal from Argonne Simulation Meeting 2004
- now implemented with Mokka CGA (geant4)

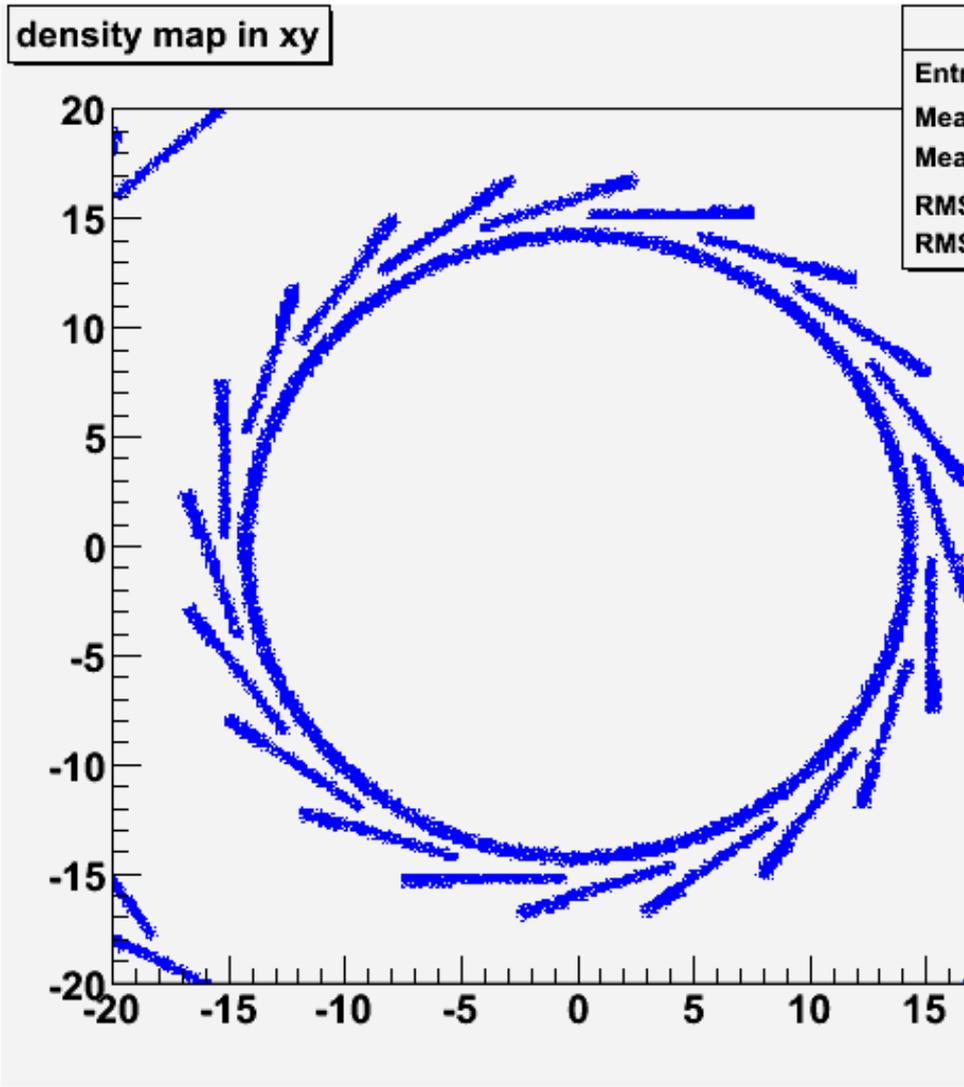
GearPointProperties

```
– GearPointProperties()
getCellID(pos : const Point3D&) : int
getMaterialName(pos : const Point3D&) : const std::string&
getDensity(pos : const Point3D&) : double
getTemperature(pos : const Point3D&) : double
getPressure(pos : const Point3D&) : double
getRadlen(pos : const Point3D&) : double
getIntlen(pos : const Point3D&) : double
getLocalPosition(pos : const Point3D&) : Point3D
getB(pos : const Point3D&) : double
getE(pos : const Point3D&) : double
getListOfLogicalVolumes(pos : const Point3D&) : std::vector< std :: string >
getListOfPhysicalVolumes(pos : const Point3D&) : std::vector< std :: string >
getRegion(pos : const Point3D&) : std::string
isTracker(pos : const Point3D&) : bool
isCalorimeter(pos : const Point3D&) : bool
```

question: is this the correct interface?

e.g. **more** needed for tracking to compute dEdx and in more compact form i.e. the **actual volumes** possibly with **averaged** material (performance)

CGAGear



- implemented by G.Musat, LLR
- to be released soon

```
CGAGearPointProperties * pointProp =  
    new CGAGearPointProperties(steer.str(),...);  
  
for(int i=0 ; i<nPoint ; ++i){  
    double xr = xmin + ( xmax - xmin ) * random();  
    double yr = ymin + ( ymax - ymin ) * random();  
  
    Point3D p( xr, yr, z0 ) ;  
  
    h1->fill( xr, yr, pointProp->getDensity( p ) ) ;  
}
```

- exact geant4 material & field information at runtime !
- performance ?
- practical issues (linking g4) ?

Gear status

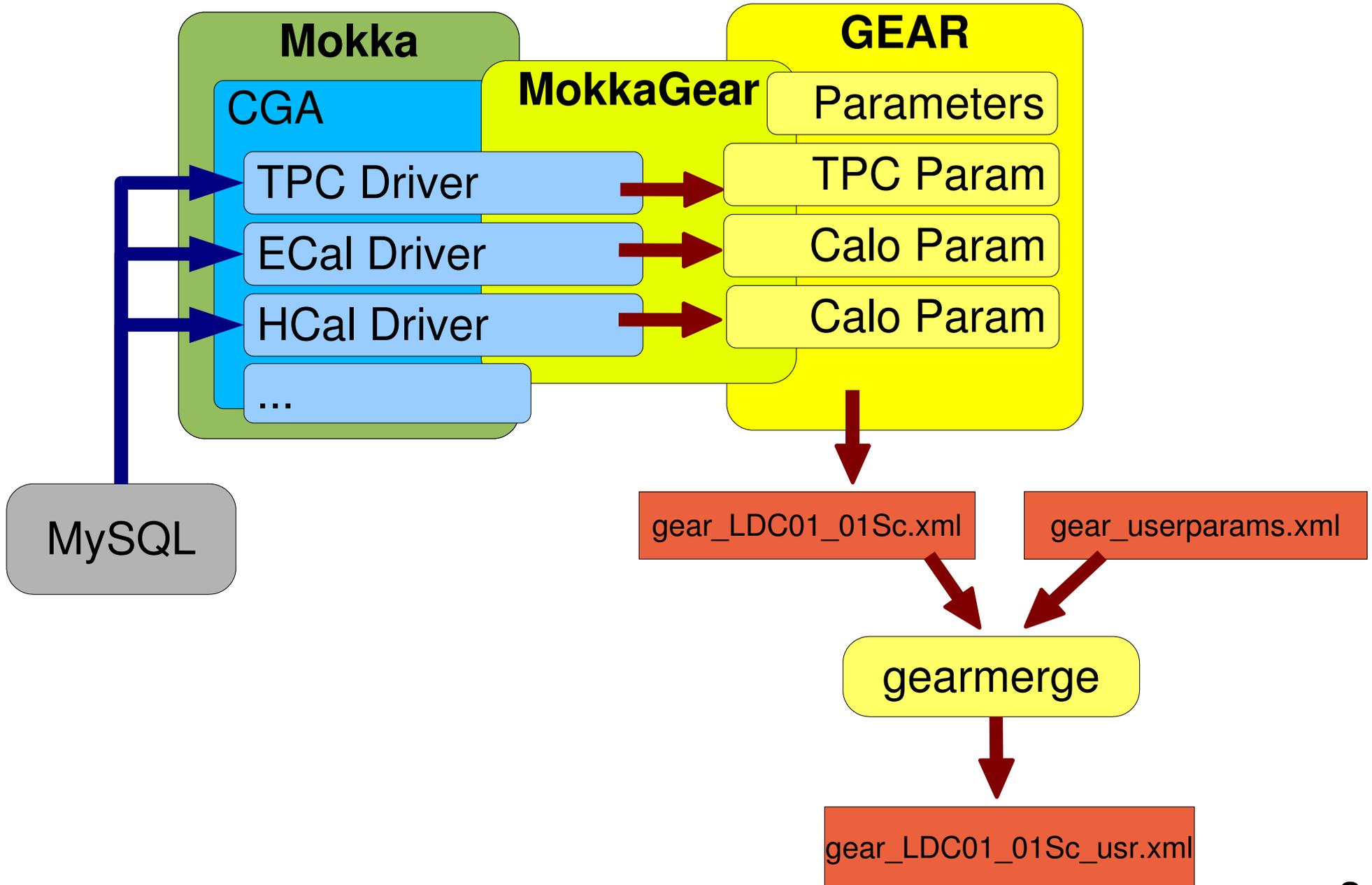
- version v00-03
 - TPC, Hcal, Ecal and VTX interfaces defined and implemented
 - user parameters
 - write xml files from parameters in memory
 - tool to merge files: [gearmerge](#)
 - [description of TPC prototypes](#) (rectangular pad plane)
 - [first version of VXD description](#)
 - GearCGA - material properties

MokkaGear

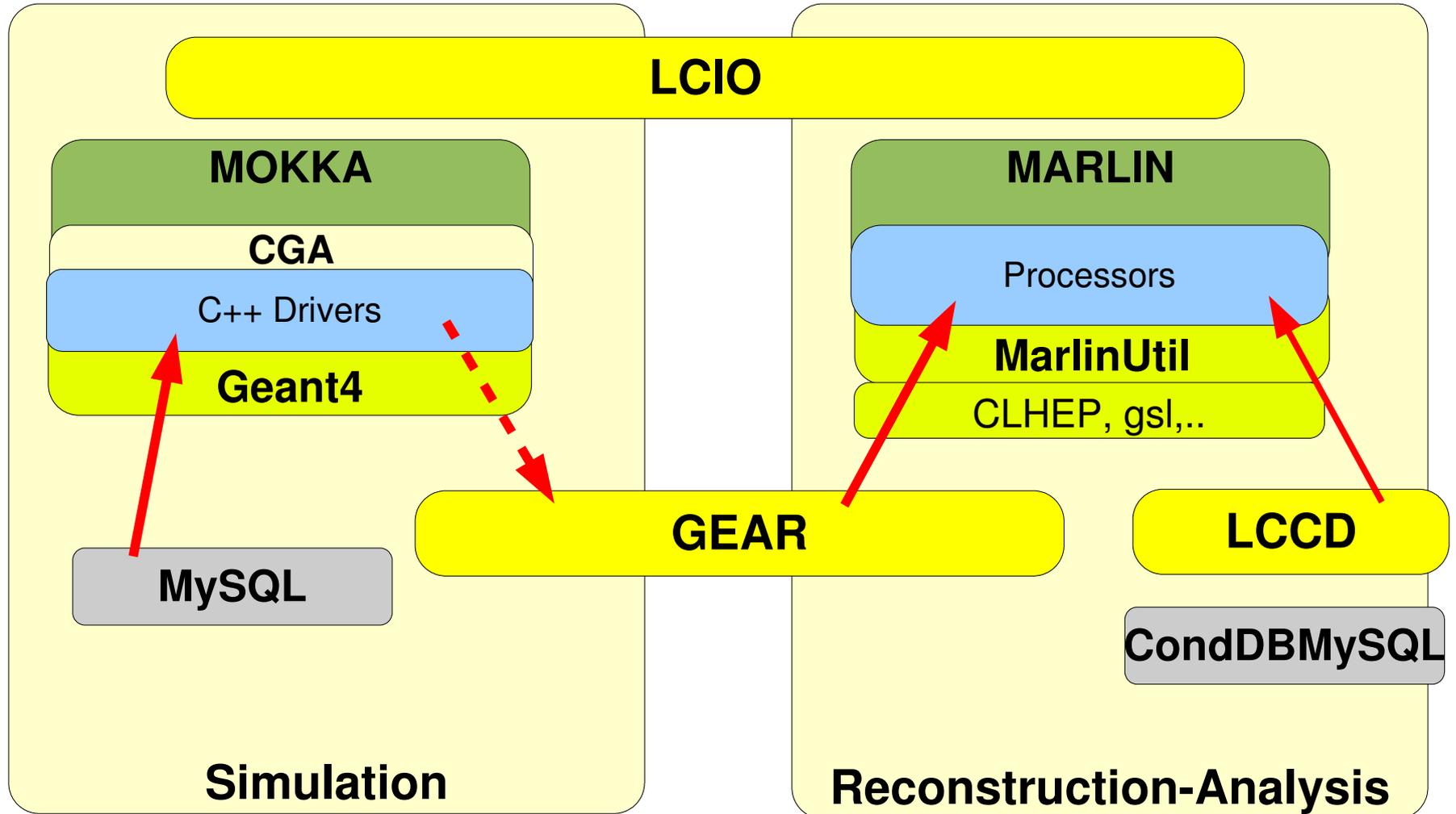
- **extension to Mokka** (R.Lippe – Diploma Thesis)
- extract geometry information in drivers when detector is built
- use Gear to create XML files for reconstruction
- currently implemented:
 - TPC (tpc04), Ecal (ecal02) and Hcal (hcal04)
- **released with Mokka 6.1**
- optional feature
 - only if Gear is installed and included

aim: have only one source of information
for describing the detector geometry !

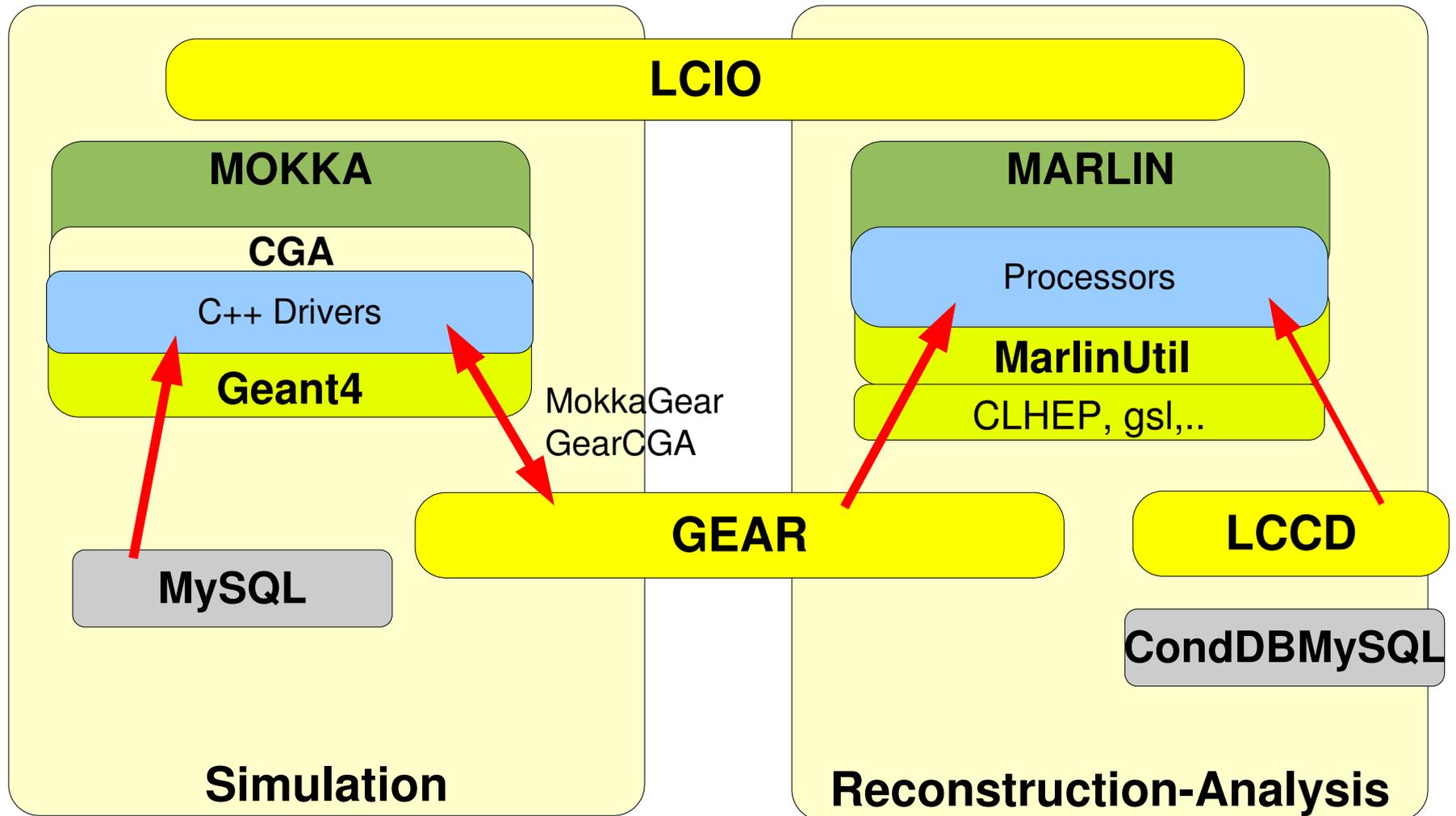
MokkaGear



LDC simulation framework



LDC simulation framework



MarlinReco

- Marlin serves as a **framework** for the distributed development of reconstruction algorithms
 - provides a well defined modularity
- MarlinReco is a **toolkit** which aims at providing reconstruction algorithms for detector concept studies
 - (almost) complete set of standard reconstruction (pflow)
 - cheaters for cross checks (and replacements)
 - all processors can seamlessly be combined together with other reconstruction code or plugged into your analysis
 - e.g. together with PandoraPFA (M.Thomson), ZVtop (LCFI)...

MarlinReco packages

- **TrackDigi**

- TPCDigi

- **new** VTXDigi

- **CaloDigi**

- LDCCaloDigi

- **Tracking**

- LEPTtracking (wrapped f77)

- **new** VTXTracking

- TrackCheater

- **Clustering**

- TrackwiseClustering

- ClusterCheater

- **Pflow**

- Wolf

- **Analysis**

- EventShapes

- SatoruJetFinder

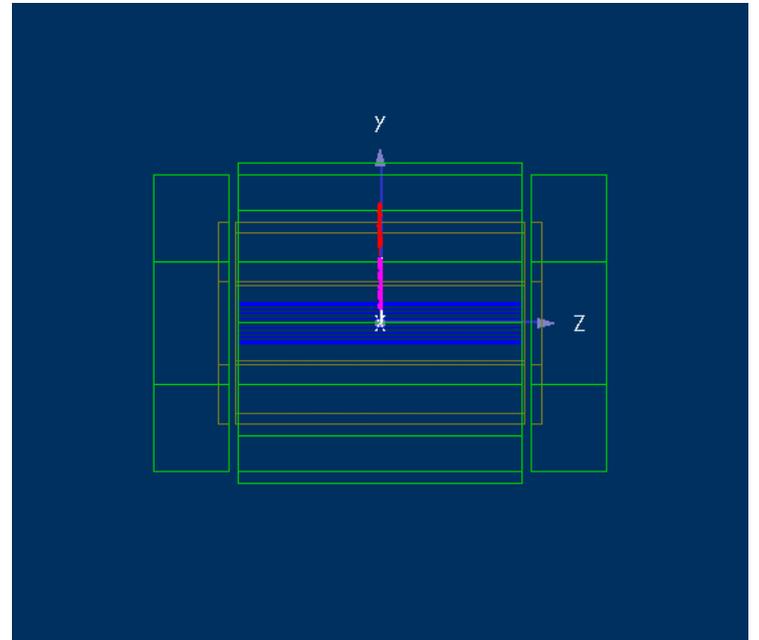
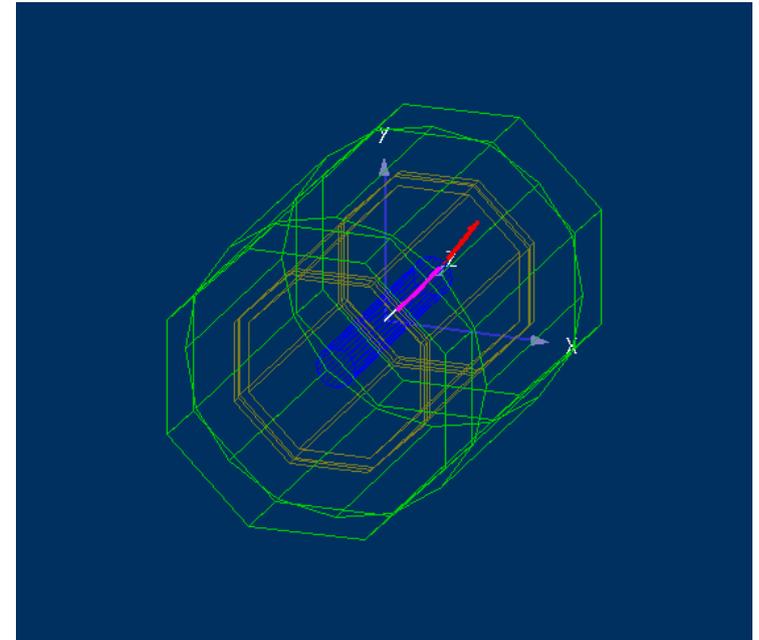
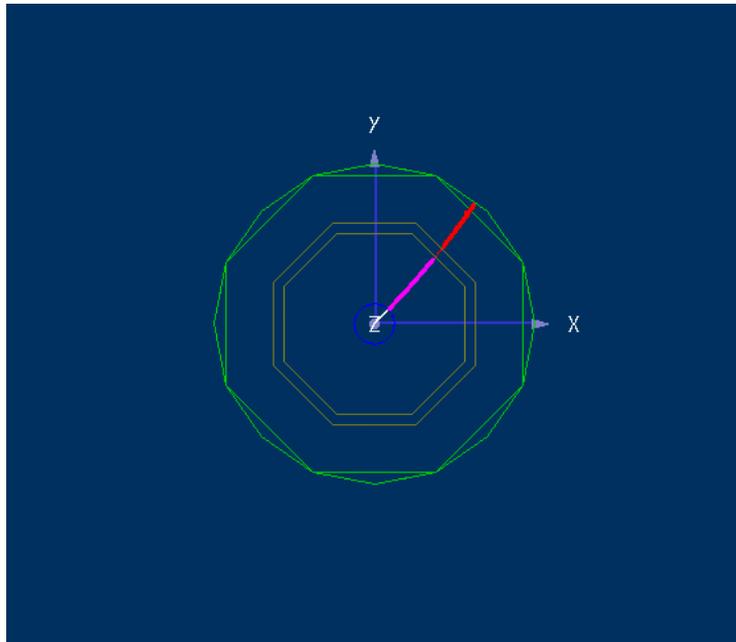
most MarlinReco processors (algorithms) are **geometry independent**
→ they can be applied to **other detector concepts** (via Gear file)

MarlinReco support packages

- **MarlinUtil** (O. Wendt)
 - Utility and Helper classes
 - helix fitter, cluster shapes,...
 - common code for CED
- **RAIDA**
 - AIDA root implementation
- **CED** (A. Zhelezov)
 - event display based on GLUT/ OpenGL
 - client server architecture
- **CEDViewer**
 - event display client processors
 - CEDViewer. GenericViewer

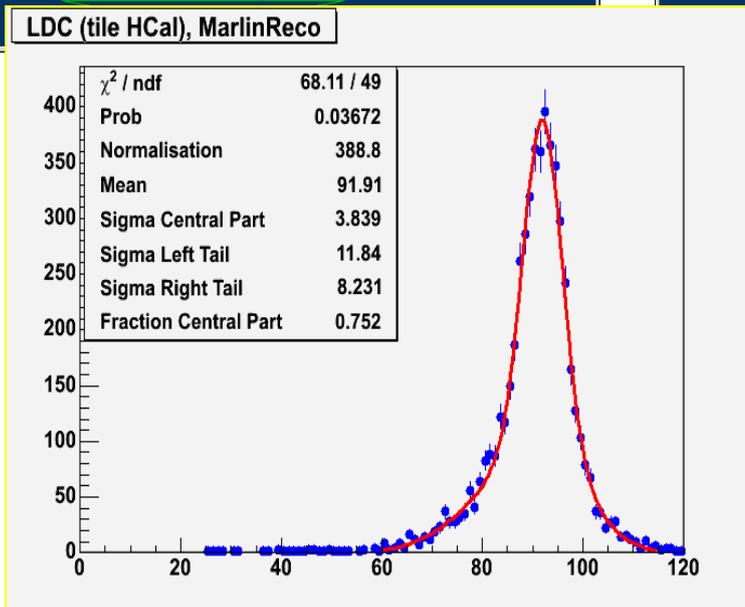
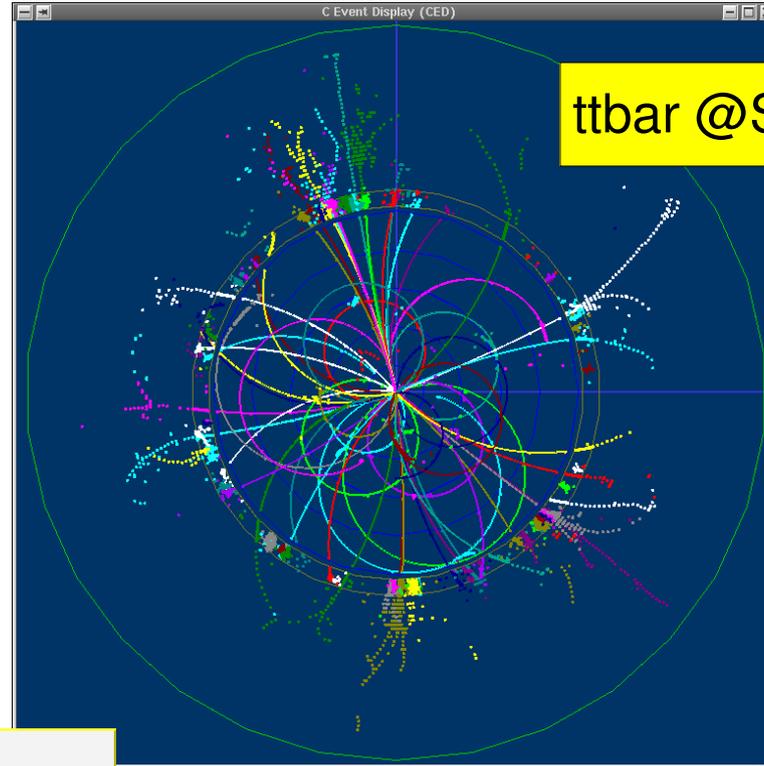
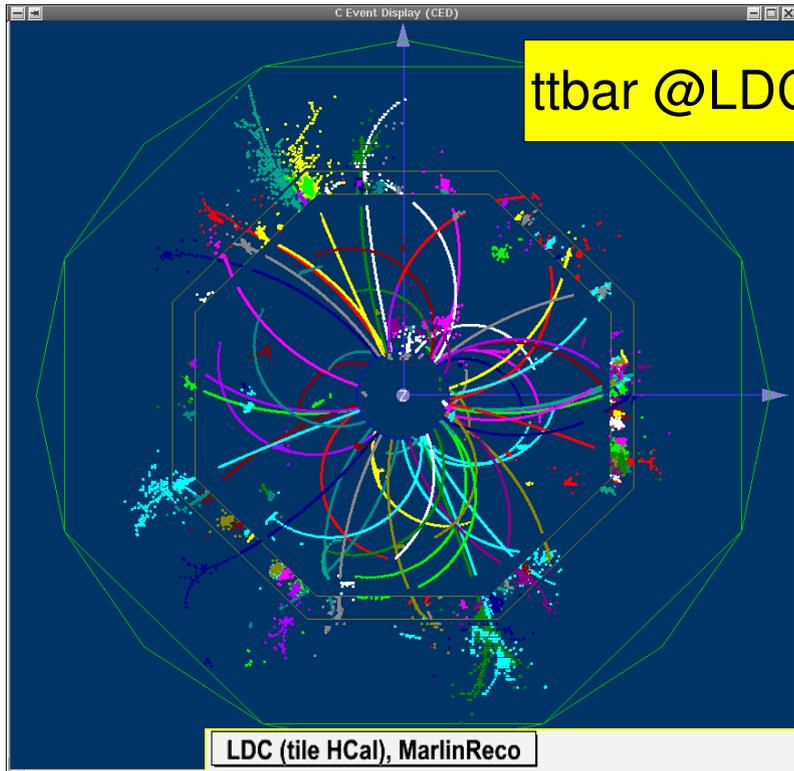
CEDViewer

simple example taken from
\$MarlinReco/examples/LDC
steer_ldc.xml
gear_ldc.xml



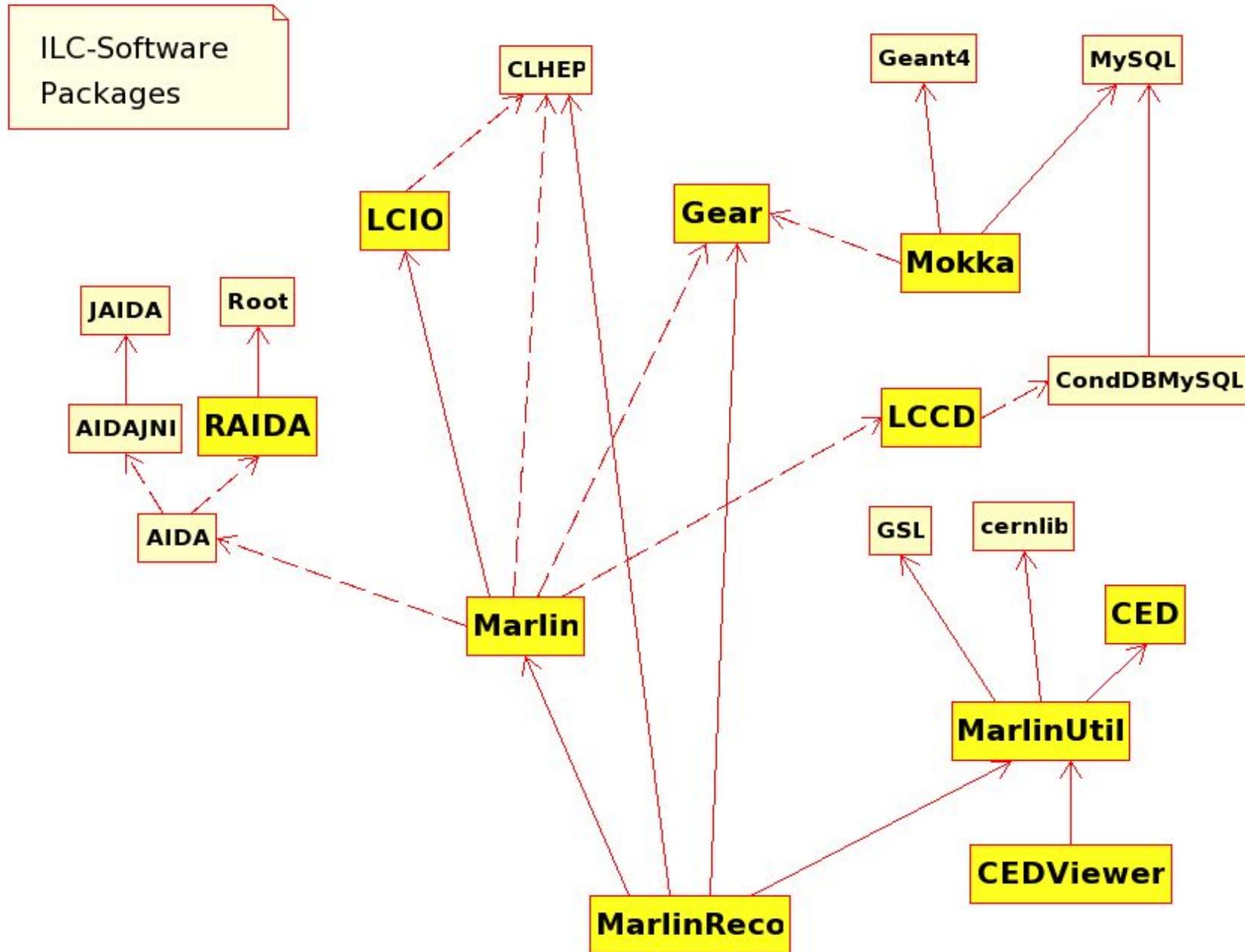
MarlinReco @work

Frank Gaede, FNAL ILC Computing Seminar, September 25, 2006



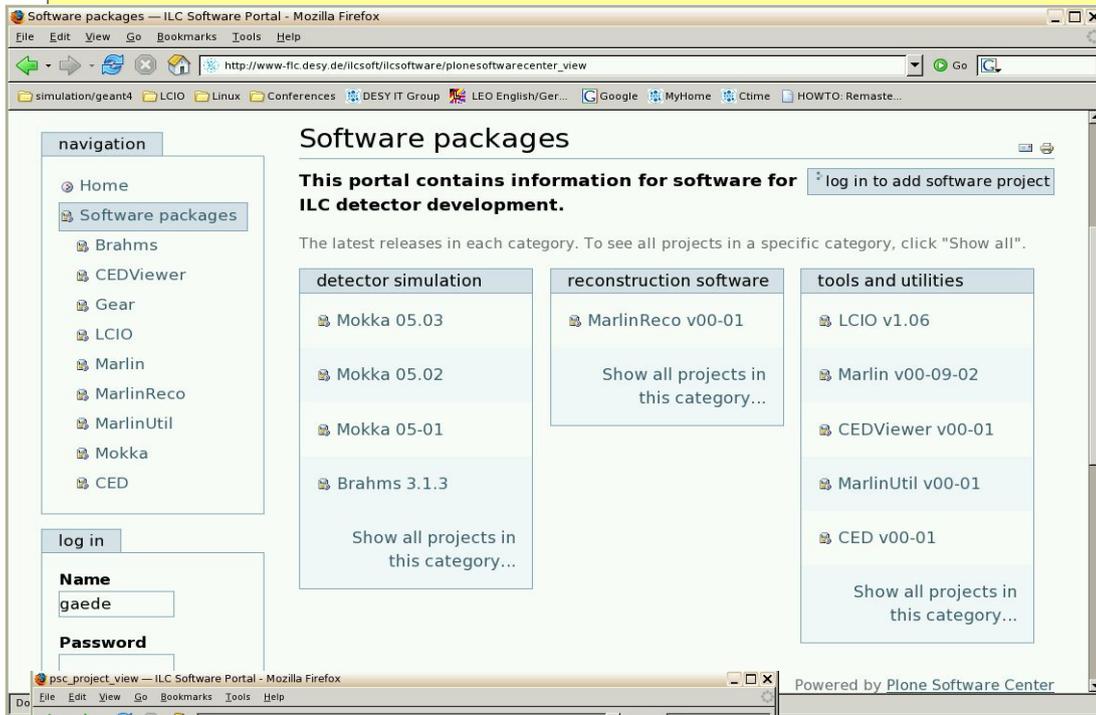
LCIO provides interoperability

software package dependencies



ILC software portal

Frank Gaede, FNAL ILC Computing Seminar, September 25, 2006



Software packages — ILC Software Portal - Mozilla Firefox

http://www.flc.desy.de/ilcsoft/ilcsoftware/plonessoftwarecenter_view

simulation/geant4 LCIO Linux Conferences DESY IT Group LEO English/Ger... Google MyHome Ctime HOWTO: Remaste...

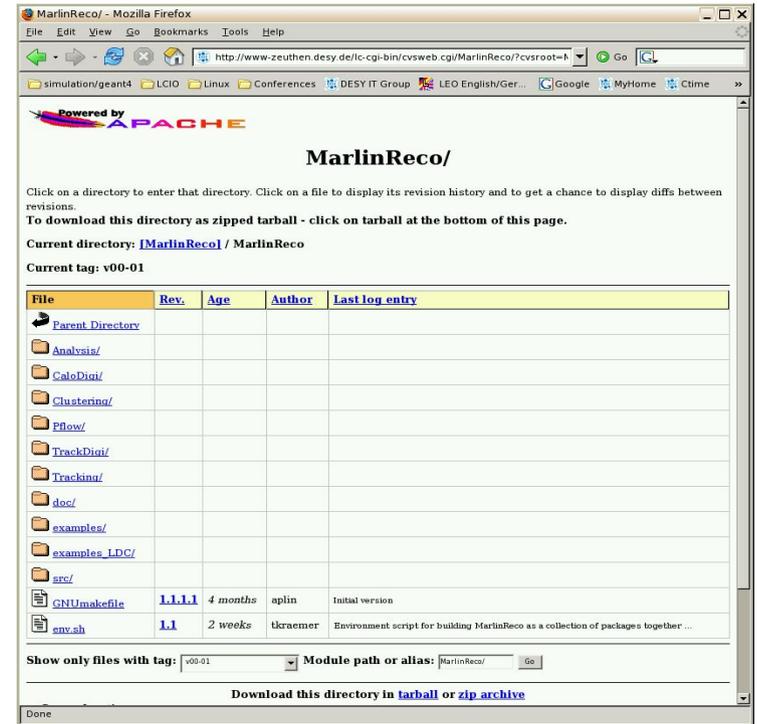
Software packages

This portal contains information for software for ILC detector development. [log in to add software project](#)

The latest releases in each category. To see all projects in a specific category, click "Show all".

detector simulation	reconstruction software	tools and utilities
<ul style="list-style-type: none">Mokka 05.03Mokka 05.02Mokka 05-01Brahms 3.1.3 Show all projects in this category...	<ul style="list-style-type: none">MarlinReco v00-01 Show all projects in this category...	<ul style="list-style-type: none">LCIO v1.06Marlin v00-09-02CEDViewer v00-01MarlinUtil v00-01CED v00-01 Show all projects in this category...

Powered by Plone Software Center



MarlinReco/ - Mozilla Firefox

http://www.zeuthen.desy.de/ilc/cgi-bin/cvsweb.cgi/MarlinReco/?cvsroot=lc

simulation/geant4 LCIO Linux Conferences DESY IT Group LEO English/Ger... Google MyHome Ctime

Powered by **APACHE**

MarlinReco/

Click on a directory to enter that directory. Click on a file to display its revision history and to get a chance to display diffs between revisions.

To download this directory as zipped tarball - click on tarball at the bottom of this page.

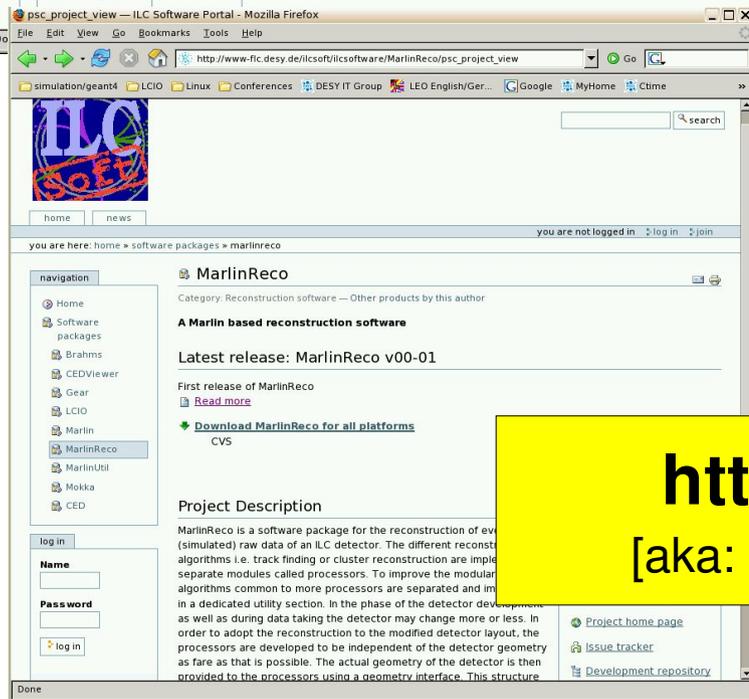
Current directory: [MarlinReco/](#) / MarlinReco

Current tag: v00-01

File	Rev.	Age	Author	Last log entry
Parent Directory				
Analysis/				
CaloDist/				
Clustering/				
Pflow/				
TrackDist/				
Tracking/				
doc/				
examples/				
examples_LDC/				
src/				
GNUmakefile	1.1.1.1	4 months	aplin	Initial version
env.sh	1.1	2 weeks	ukraemer	Environment script for building MarlinReco as a collection of packages together ...

Show only files with tag: Module path or alias: [Go](#)

[Download this directory in tarball or zip archive](#)



pssc_project_view — ILC Software Portal - Mozilla Firefox

http://www.flc.desy.de/ilcsoft/ilcsoftware/MarlinReco/pssc_project_view

simulation/geant4 LCIO Linux Conferences DESY IT Group LEO English/Ger... Google MyHome Ctime

home news

you are here: home > software packages > marlinreco

MarlinReco

Category: Reconstruction software — Other products by this author

A Marlin based reconstruction software

Latest release: MarlinReco v00-01

First release of MarlinReco [Read more](#)

[Download MarlinReco for all platforms](#)

CVS

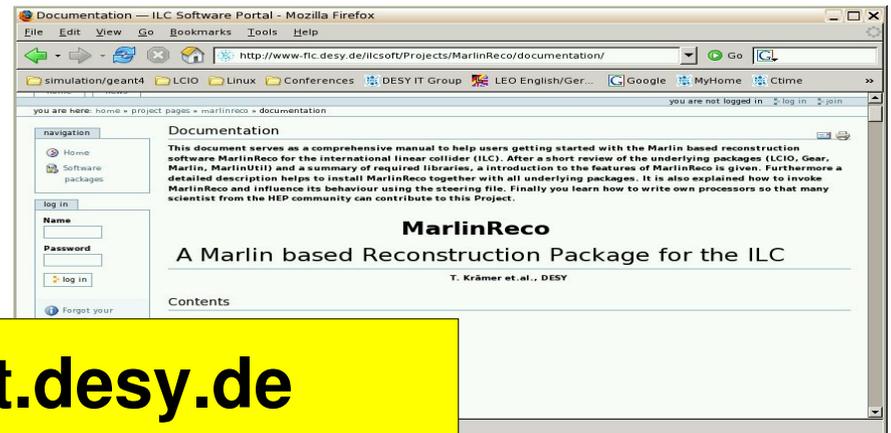
Project Description

MarlinReco is a software package for the reconstruction of event (simulated) raw data of an ILC detector. The different reconstruction algorithms i.e. track finding or cluster reconstruction are implemented as separate modules called processors. To improve the modular structure, the algorithms common to more processors are separated and implemented in a dedicated utility section. In the phase of the detector development as well as during data taking the detector may change more or less. In order to adopt the reconstruction to the modified detector layout, the processors are developed to be independent of the detector geometry as far as that is possible. The actual geometry of the detector is then provided to the processors using a geometry interface. This structure

[Project home page](#)

[Issue tracker](#)

[Development repository](#)



Documentation — ILC Software Portal - Mozilla Firefox

http://www.flc.desy.de/ilcsoft/Projects/MarlinReco/documentation/

simulation/geant4 LCIO Linux Conferences DESY IT Group LEO English/Ger... Google MyHome Ctime

you are here: home > project pages > marlinreco > documentation

Documentation

This document serves as a comprehensive manual to help users getting started with the Marlin based reconstruction software MarlinReco for the international linear collider (ILC). After a short review of the underlying packages (LCIO, Gear, Marlin, MarlinUtil) and a summary of required libraries, an introduction to the features of MarlinReco is given. Furthermore a detailed description helps to install MarlinReco together with all underlying packages. It is also explained how to invoke MarlinReco and influence its behaviour using the steering file. Finally you learn how to write own processors so that many scientist from the HEP community can contribute to this Project.

MarlinReco

A Marlin based Reconstruction Package for the ILC

T. Krämer et al., DESY

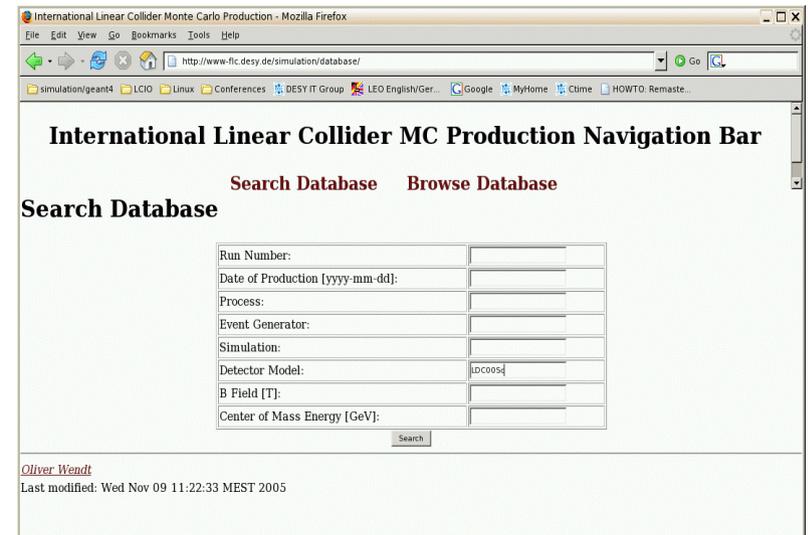
Contents

<http://ilcsoft.desy.de>
[aka: <http://www-flc.desy.de/ilcsoft>]

ILC grid - “mass production”

- detector optimization – vary
 - B,R_TPC,L_TPC,...
- need considerable number of events with detector parameter variations for benchmark reactions
- produced these files on the **grid** for VO ILC – 450 keVts:
 - Z0 and uds, ccbb , ttbar, WW, ZH @ 500 GeV
 - 4 detector variants, 3 T and 4 T field
- database with available data files
- use **grid tools** to distribute/download the data !

- provide the simulated data that's needed
- exercise the software & computing infrastructure



International Linear Collider Monte Carlo Production - Mozilla Firefox

http://www.ftc.desy.de/simulation/database/

International Linear Collider MC Production Navigation Bar

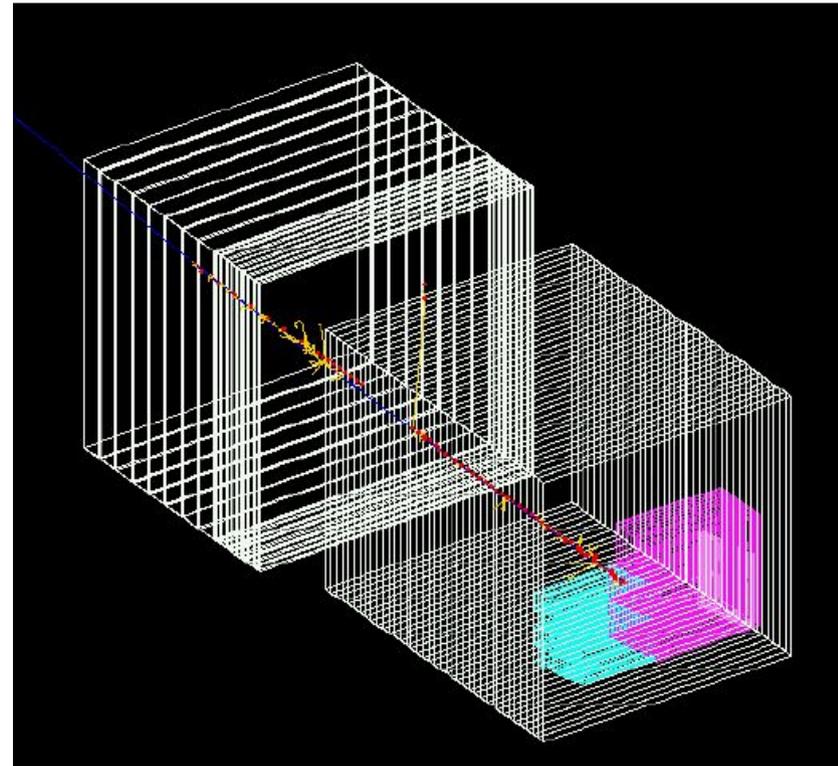
Search Database Browse Database

MC data-files matching your query:

Run Number	Event Generator	Simulation	Detector Model	B Field [T]	Center of Mass Energy [GeV]
zpole_noisr_LDC00Sc_6.0T_r1690_12730_LCPhys_5	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2
zpole_noisr_LDC00Sc_6.0T_r1690_12730_LCPhys_4	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2
zpole_noisr_LDC00Sc_6.0T_r1690_12730_LCPhys_3	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2
zpole_noisr_LDC00Sc_6.0T_r1690_12730_LCPhys_2	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2
zpole_noisr_LDC00Sc_6.0T_r1690_12730_LCPhys_1	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2
zpole_noisr_LDC00Sc_4.0T_r1690_12730_LCPhys_5	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2
zpole_noisr_LDC00Sc_4.0T_r1690_12730_LCPhys_4	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2
zpole_noisr_LDC00Sc_4.0T_r1690_12730_LCPhys_3	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2
zpole_noisr_LDC00Sc_4.0T_r1690_12730_LCPhys_2	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2
zpole_noisr_LDC00Sc_4.0T_r1690_12730_LCPhys_1	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2
zpole_noisr_LDC00Sc_2.0T_r1690_12730_LCPhys_5	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2
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zpole_noisr_LDC00Sc_2.0T_r1690_12730_LCPhys_3	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2
zpole_noisr_LDC00Sc_2.0T_r1690_12730_LCPhys_2	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2
zpole_noisr_LDC00Sc_2.0T_r1690_12730_LCPhys_1	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2
Mokka 5.03pre	LDC00Sc	4	500		
Mokka 5.03pre	LDC00Sc	4	500		
Mokka 5.03pre	LDC00Sc	4	500		
Mokka 5.03pre	LDC00Sc	4	500		

CALICE testbeam

- testbeams for CALICE prototypes (Ecal, Hcal, Tailcatcher)
- DESY 2005:
 - e- 1-6 GeV
- CERN/FNAL 2006/2007
 - mu,pi,p 1-100GeV
- $O(10^8)$ events
- $n \cdot O(10^8)$ Monte Carlo events
- $\sim 20\,000$ channels

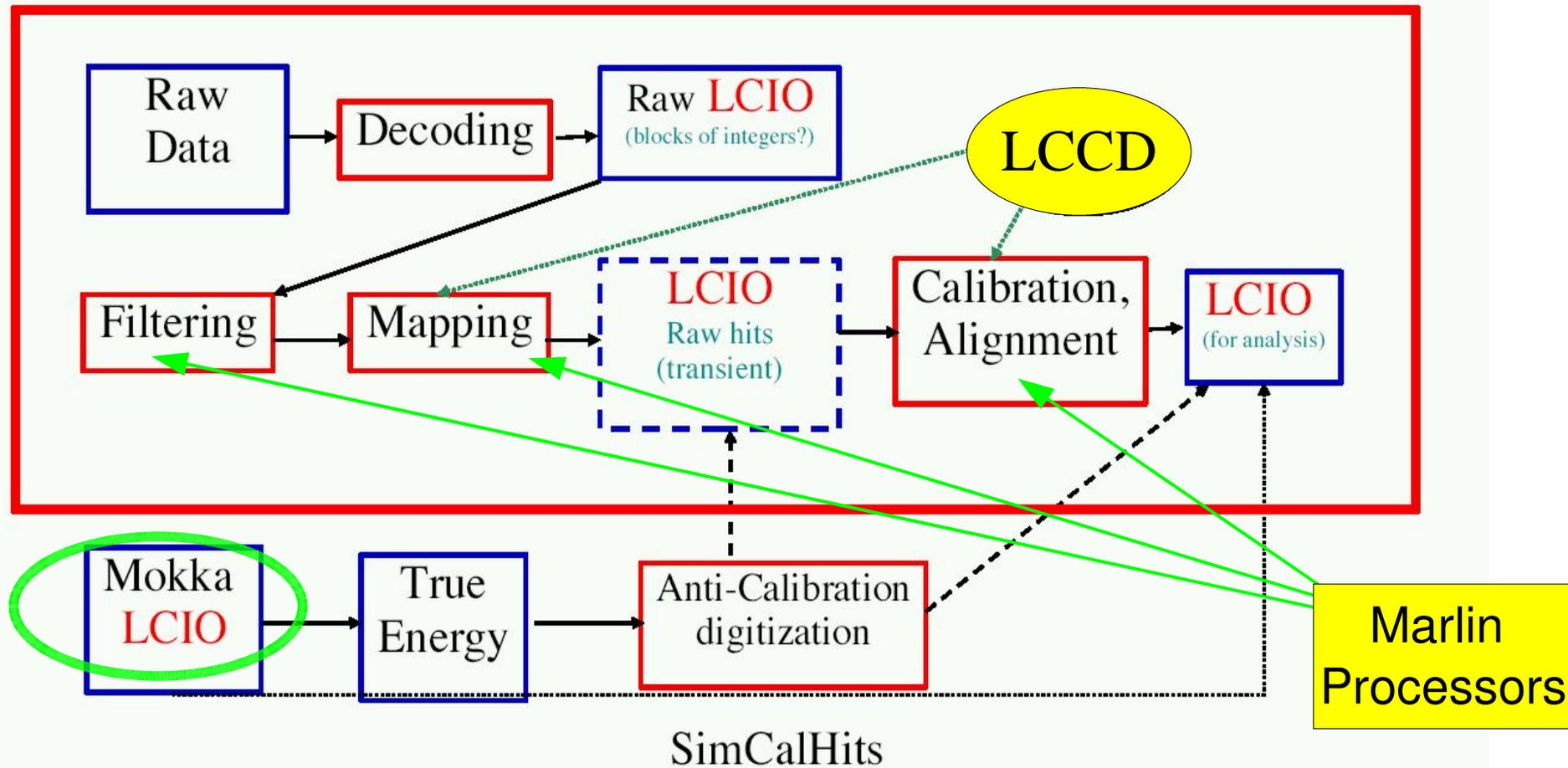


- detector R&D
 - test DAQ
 - test detector concepts
- software
 - hadronic physics in Geant4
 - **test complete software chain !**

Calice testbeam software

Data Processing Scheme

Calibration/Analysis Steps use LCIO as backbone



Interoperability of ILC software I

- the **interoperability** of the ILC software frameworks is a key ingredient for collaboration on **optimizing the detector**
- **LCIO as a persistency format and event data model provides a minimal basis for the interoperability:**
 - exchange of software that uses LCIO as input and output
 - exchange of data files (e.g. from g4-based full simulation)
 - use LCIO files as intermediate glue between modules
- however still a lot of double work exists:
 - geometry definition
 - tracking (pattern recognition, Kalman filter)
 - vertexing
 - similar algorithms in different frameworks (languages Java/C++)

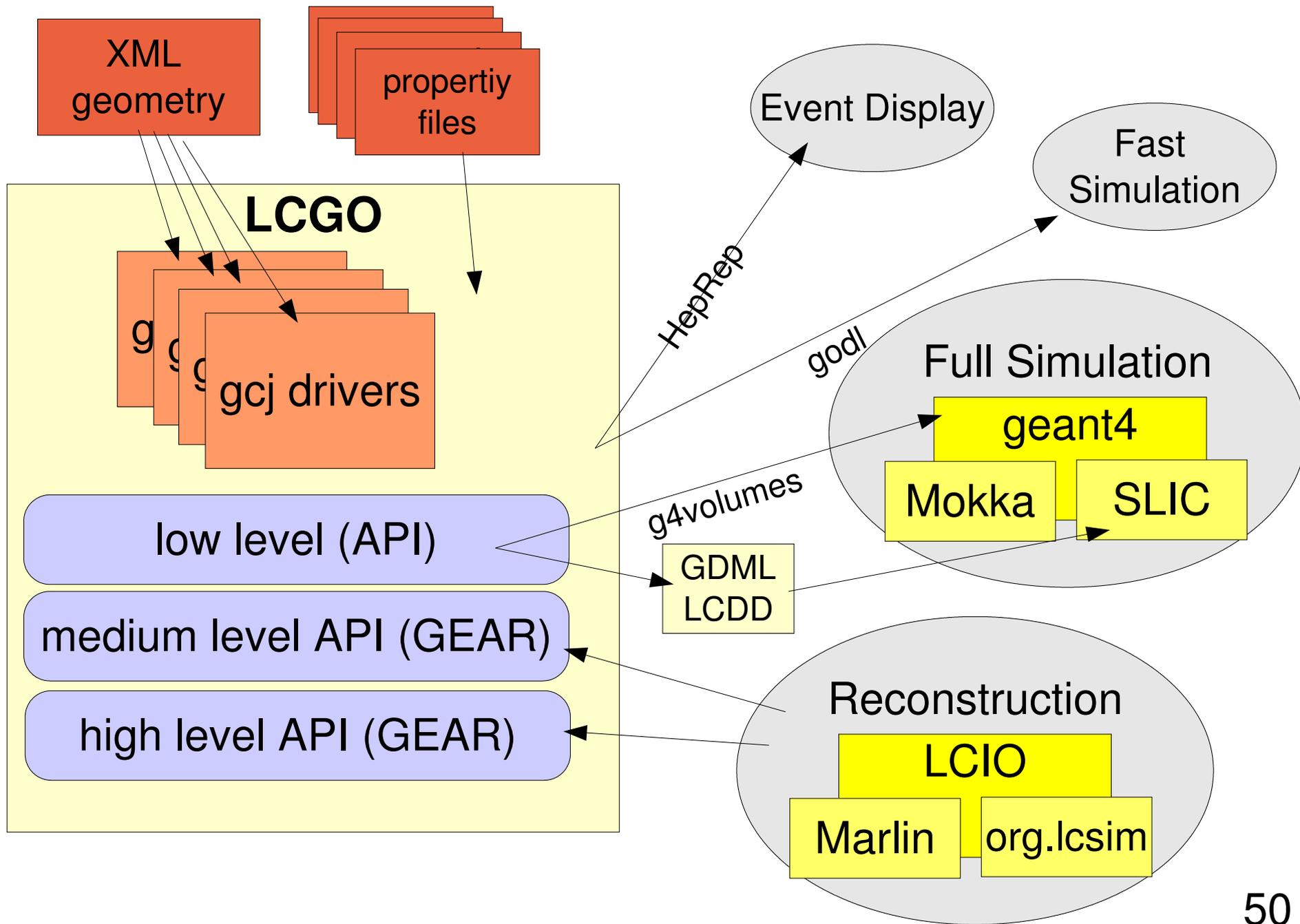
Interoperability of ILC software II

- next step of inter operation is to use **software modules developed in a different framework**
- example prototypes: org.lcsim(Java) vs. Marlin(C++)
- **calling Marlin processor from Java main program:**
 - use SWIG to create Java binding of Marlin/LCIO (SLAC)
- **calling org.lcsim drivers from Marlin main:**
 - write/read LCIO data to/from stream in memory in between calls to different language modules (DESY)
- promising first results, however a number of technical issues need to be resolved
- problem: two independent (somewhat similar) ways of defining the geometry in the two frameworks
- -> **need common geometry package**

A Common Geometry Toolkit

- **LCGO**: A common geometry toolkit to be used in all (?) ILC frameworks
 - SLAC-DESY project - initially
 - -> of course open for all collaborators, e.g. FNAL !
- requirements/goals for LCGO:
 - be at least as functional as existing systems (org.lcsim, GEAR, Mokka, SLIC,...)
 - enable smooth transition path from existing systems
 - encourage/increase interoperability between systems
 - have no known principle short comings: “everything should be possible”

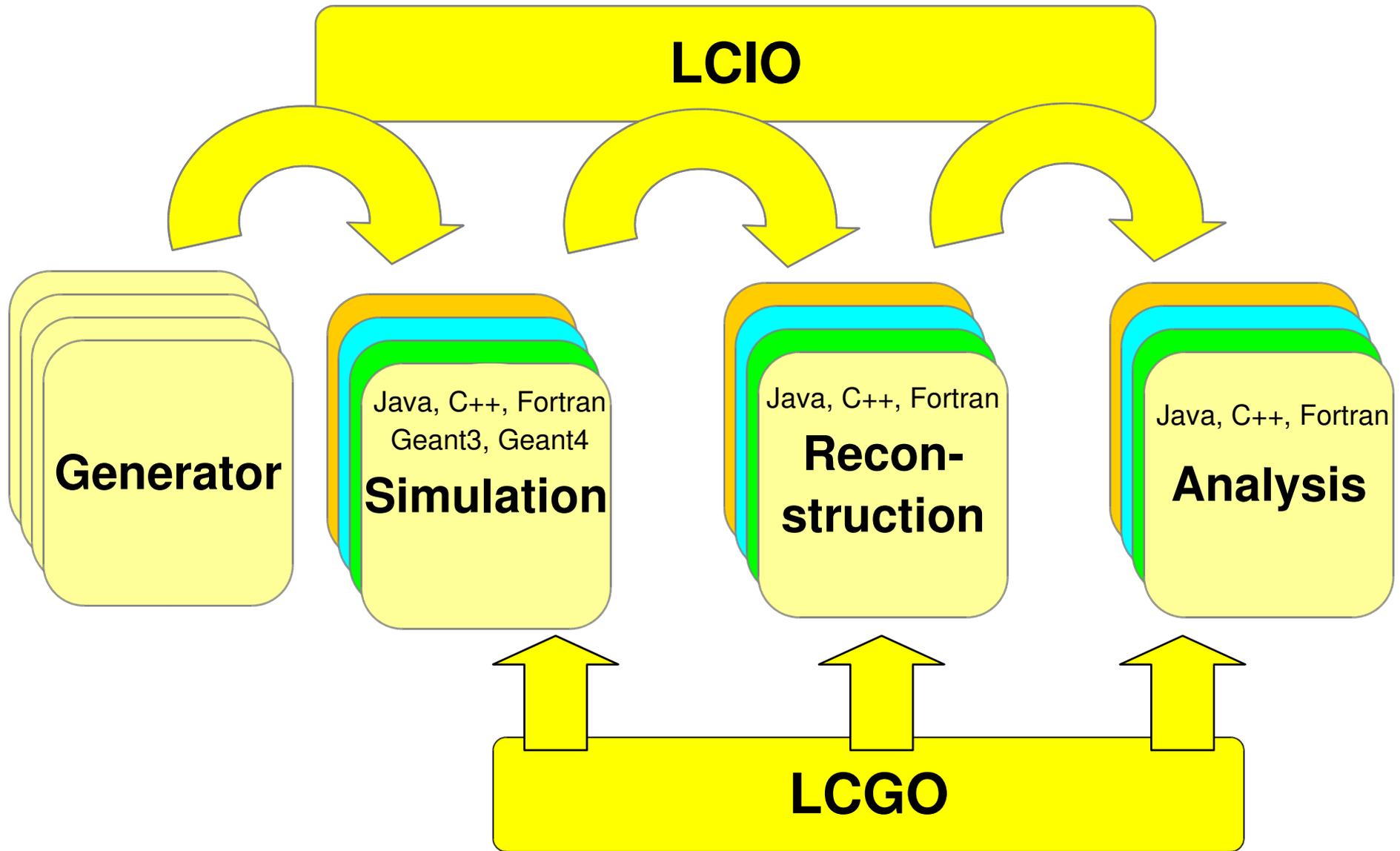
LCGO implementation prelim.



some LCGO planned features

- extended GEAR interface (medium and high level)
- tracking (and clustering PFA)
- average material volumes
- intersection with 'next' volume
- dE/dx
- field maps
- access to volumes
- extensions of detectors (a la gear)
 - e.g. #layers, thickness, width,...
- material database
- field maps
- properties (sampling fractions)
- readout properties
 - cellId <-> position
 - cellid range (noise simulation)
 - cell sizes
 - neighbors
- Vector and Matrix classes ?
 - ThreeVector, Point3D
 - Planes, cylinders, ... ?
 - FourVector
 - SymMatrix (covariances)

ILC interoperable software chain



Summary

- a fairly complete OO-software framework exists for the LDC study based on **Mokka, Marlin, LCIO, LCCD and GEAR**
- used for detector concept study
- to be extended with **LCGO**

details @ software portal:
<http://ilcsoft.desy.de/>

GOAL:

- **increase interoperability with other frameworks**
- **unify rather than duplicate**
- **save man power to work on real issues like**
- **reconstruction, i.e. Tracking, PFA,...**

Please consider using common software tools
in particular **LCIO**
for your ILC study and provide feedback
and **contribute** to the effort !

Backup slides ...

Monte Carlo

MCParticle

- Kinematics (4Vector)
- Parents/Daughters
- Generator Status
- PID
- Vertex
-
- -> all of HEPEVT
- + Simulator Status
- + Endpoint

SimCalorimeterHit

- CellID
- Energy/Amplitude
- Position (opt.)
- **MCParticle Contributions**

SimTrackerHit

- Position
- dEdx
- **MCParticle Contribution**

Datamodel IV

RawData and Digitization

RawCalorimeterHit

- cellID
- amplitude
- time (opt.)

CalorimeterHit

- cellID
- energy
- time (opt.)
- position (opt.)

use abstract hit classes as input to reconstruction

TrackerRawData

- cellID
- time
- adc[] *int*

TPCHit replaced by more generic raw tracker data classes

TrackerData

- cellID
- time
- charge[] *float*

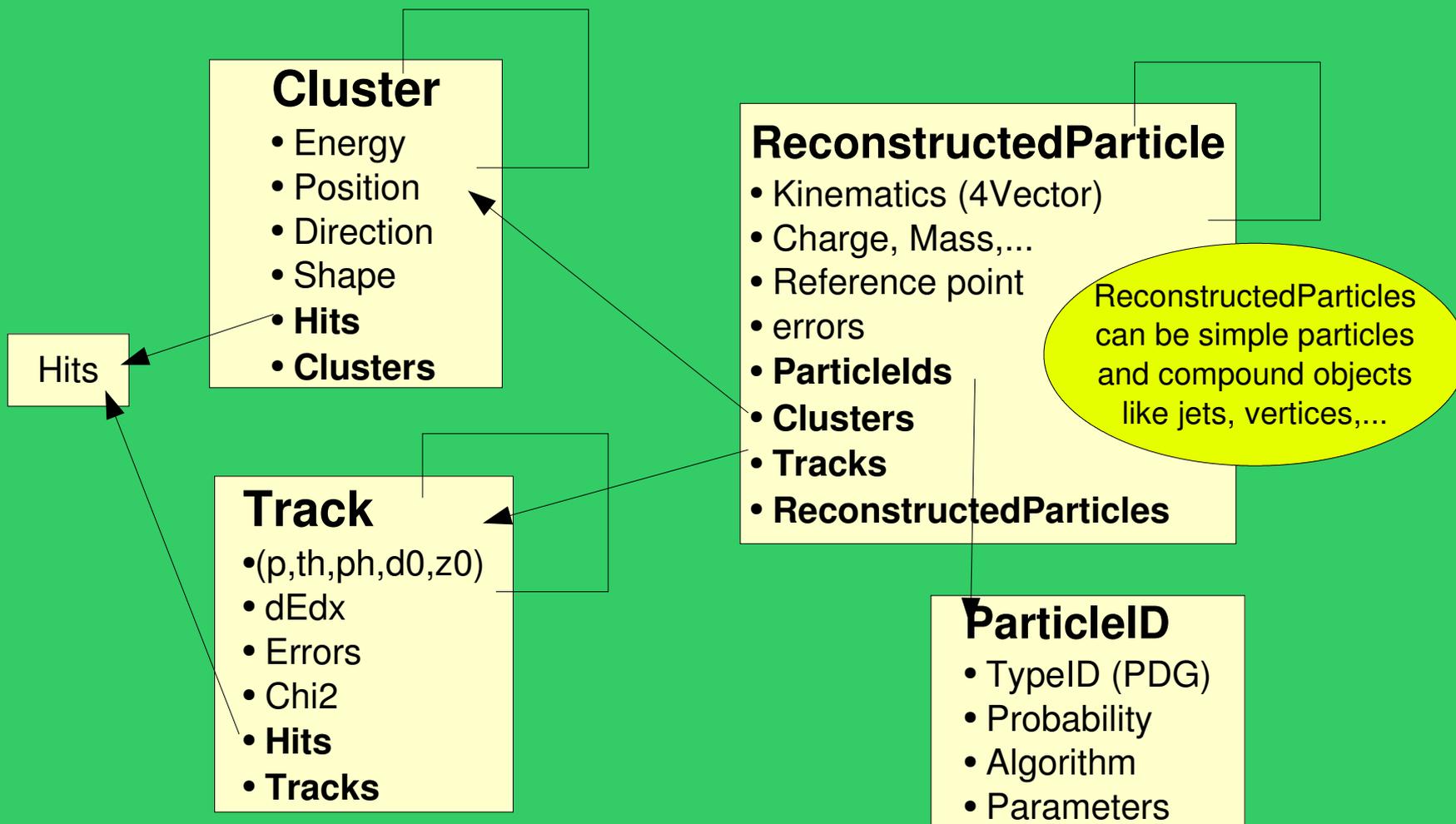
TrackerHit

- position (x,y,z)
- covariance
- dEdx
- position (opt.)

TrackerPulse

- cellID
- time
- charge

Reconstruction & Analysis



LCIO Future Plans

- current data model fairly complete
 - check usability of data model, e.g. track parameters
 - ongoing through development of reconstruction code !
 - need to define conventions on how to use LCIO
 - collection names, object types, collections to be present in event
 - see talk by
- need to make LCIO more convenient (and efficient)
 - decoding of MCParticle information (parent/daughter, ...)
 - inverse relations (get all tracks for one MCParticle)
 - attach user information to LCObjects
- would like to make C++ version more C++ like, e.g. allow to use STL algorithms (templates in general)
 - planed for LCIO v02-00
- **need user input !!**

LCIO status [v01-07]

- added optional **momentum[3]** and **pathLength** to SimTrackerHit (silicon digitization)
- LCReader::skipNEvents()
 - dump the n-th event in \$LCIO/bin/dumpevent
- **C++ utility code for encoding/decoding of cellids in hit classes (32bit and 64bit)**
- support for large files (>2GB) and UTIL::LCSplitWriter
- optional **python binding** (J.McCormick)
 - files are downward compatible with LCIO 1.6
 - see \$LCIO/doc/versions.readme for more

Future plans - activities

- short/mid term:
 - interoperability with other frameworks
 - interface Java/C++ based on LCIO event data model
 - unify the geometry description based on xml (Gear/LCCD)
 - improve/extend software
 - PFA algorithms, track reconstruction,...
 - event display, conditions db,....
- mid/long term:
 - investigate a new data storage format for LCIO (possibly based on rootIO)
 - ...